

• Introduction.

01/09/2024

→ Systems that evolve in space & time are described by PDEs.

{ PDE: An equation that relates a multivariate function ψ and its partial derivatives in 2 or more independent variables. }

• ψ is tensor $\begin{cases} \text{Scalar} \\ \text{vector} \\ \text{tensor} \end{cases}$ Example: (Advection) $\begin{cases} \frac{\partial \rho}{\partial t} + u \cdot \frac{\partial \rho}{\partial x} = 0 & (1D) \\ \frac{\partial \rho}{\partial t} + (\mathbf{u} \cdot \nabla) \rho = 0 & (ND) \end{cases}$

• Check linearity of a solution: if $L(\phi)$ is solution \rightarrow check if $L(\alpha\phi_1 + \beta\phi_2) \stackrel{(1)}{=} \alpha L(\phi_1) + \beta L(\phi_2)$

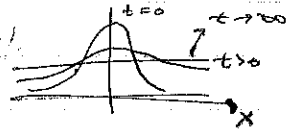
• Conservation (ND) $\rightarrow \frac{\partial \phi}{\partial t} + \nabla \cdot \vec{F} = 0$ ($\vec{F} = \vec{F}(\psi)$)

• Non-linear Advection eqn. (Burger's eqn.) $\rightarrow \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = 0$ (inviscid Burgers)

\hookrightarrow Use "Characteristics methods" Non-linear P.D.E.

• Diffusion eqn. $\rightarrow \frac{\partial T}{\partial t} = \alpha \frac{\partial^2 T}{\partial x^2}$ ($\alpha = \frac{k}{\rho c_p}$ = thermal diffusivity)

\downarrow Heat, Mass, Concentration, Momentum, ... $\hookrightarrow \frac{\partial T}{\partial t} = \alpha \nabla^2 T$ (ND)



• Derivation of P.D.E.

$\begin{matrix} \uparrow F_{y+dy} \\ \uparrow F_x \\ \downarrow F_y \\ \downarrow F_{x-dx} \end{matrix}$ $(\rho dy) \rho c_p \frac{\partial T}{\partial t} = (F_x - F_{x+dx}) dy + (F_y - F_{y+dy}) dx$ (flux) (going in is +)

$\Rightarrow -\rho c_p \frac{\partial T}{\partial t} = \left\{ \frac{\partial F}{\partial x} + \frac{\partial F}{\partial y} \right\}$

$\Rightarrow -\rho c_p \frac{\partial T}{\partial t} = -k \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right) = -k \nabla^2 T$

(Four's law: $F_x = -k \frac{\partial T}{\partial x}$)

$\Rightarrow \frac{\partial T}{\partial t} = \alpha \nabla^2 T$ (3) ✓

We can also argue $\rho c_p \frac{\partial T}{\partial t} + \nabla \cdot \vec{F} = 0$ (Conservation law) (1)

$\Rightarrow \rho c_p \frac{\partial T}{\partial t} + \nabla \cdot (-k \nabla T)$

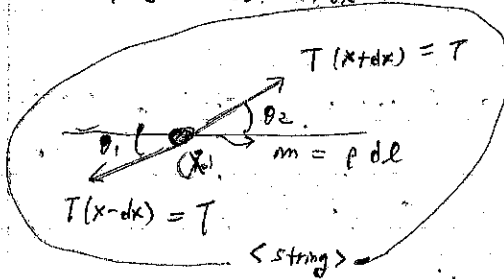
$\Rightarrow \frac{\partial T}{\partial t} = \alpha \nabla^2 T$ (3) ✓

$$\frac{\partial T}{\partial t} = \alpha \nabla^2 T \xrightarrow{\text{steady state}} \left. \begin{aligned} \nabla^2 T &= 0 \quad (\text{Laplace eqn.}) \\ \nabla^2 T &= S \quad (\text{Poisson's eqn.}) \\ &\downarrow \text{Heat source} \end{aligned} \right\}$$

• Vibration / waves.

$$\frac{\partial^2 u}{\partial t^2} - c_0^2 \frac{\partial^2 u}{\partial x^2} = 0 \quad \xrightarrow{(4)} \quad \frac{\partial^2 u}{\partial t^2} - c_0^2 \nabla^2 u = 0 \quad (\text{d'Alembert's eqn.})$$

(wave equation)



• Classification of PDE. $\phi(x, y)$ for examples

① order / degree

First order: $a(\phi, x, y) \frac{\partial \phi}{\partial x} + b(\phi, x, y) \frac{\partial \phi}{\partial y} + c(\phi, x, y) + d(x, y) = 0$

Second order: $A(\frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \phi, x, y) \phi_{xx} + B(\dots) \phi_{xy} + C(\dots) \phi_{yy} = 0$
(First order terms = 0)

How to discriminate?

Suppose $A^2 + B^2 + C^2 \neq 0$, ① $B^2 - 4AC > 0$: Hyperbolic (wave eqn.)

⇒ information traveling

② $B^2 - 4AC = 0$: Parabolic (diffusion)

③ $B^2 - 4AC < 0$: Elliptic (Laplace, Poisson)

(1) Linear

(2) Homogeneous

(3) Init. Cond. / Bound. Cond. → well-posedness.

↓
Depends on domain / indep. variables.

• Solution methods:

1) Characteristics

2) Separation of var.

3) Integral transformation

4) Similarity solution

Linear

Non-linear

○

○

○

x

○

x

○

○

Goal: PDE → ODE

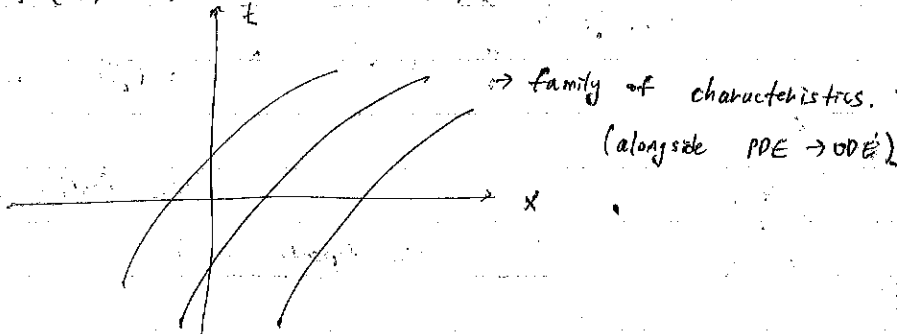
separation

First order / ... order PDEs

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First order PDE.

$$A(\psi, x, t) \frac{\partial \psi}{\partial t} + B(\psi, x, t) \frac{\partial \psi}{\partial x} + C(\psi, x, t) + D(x, t) = 0 \quad \text{--- ①}$$



$\psi(x, t)$ on trajectory of $\psi(x(s), t(s))$

$$\frac{d\psi}{ds} = \frac{\partial \psi}{\partial x} \frac{dx}{ds} + \frac{\partial \psi}{\partial t} \frac{dt}{ds} \quad \text{--- ②}$$

If $A \neq 0 \Rightarrow ② \rightarrow ① \Rightarrow \frac{d\psi}{ds} + \frac{B}{A} \frac{dx}{ds} + \frac{C+D}{A} = 0 \quad \text{--- ③}$

$$\Rightarrow ① = \frac{\partial \psi}{\partial x} \left\{ \frac{dx}{ds} - \frac{B}{A} \frac{dt}{ds} \right\} - \frac{C+D}{A} \frac{dt}{ds} = \frac{d\psi}{ds}$$

$$\Rightarrow \frac{d\psi}{dx} \left\{ \frac{dx}{ds} - \frac{B}{A} \frac{dt}{ds} \right\} - \frac{C+D}{A} \frac{dt}{ds} = \frac{d\psi}{ds} \quad \text{--- ④}$$

③ also becomes d/dt form

Choose $(s=t) \Rightarrow \frac{dt}{ds} = 1, \quad \frac{dx}{dt} = v$

For ④ to hold, $\frac{dx}{ds} - \frac{B}{A} \frac{dt}{ds} = 0$ and $\frac{d\psi}{ds} = - \frac{C+D}{A} \frac{dt}{ds}$

\therefore It has to satisfy for arbitrary (s) .

$$\therefore \frac{dx}{dt} = \frac{B(\psi, x, t)}{A(\psi, x, t)} \quad \text{and} \quad \frac{d\psi}{dt} = - \frac{C(\psi, x, t) + D(x, t)}{A(\psi, x, t)}$$

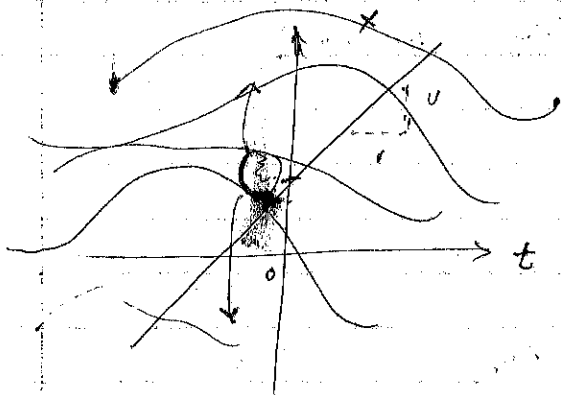
PDE \rightarrow 2 distinct ODEs ; These are called,

Family of characteristic curves, $(x(s), t(s), \psi(s))$

As information (s) flows, (information flow occurs),
the ψ function evolves through the (information) flow.

Example.

① $\frac{\partial \phi}{\partial t} + U \frac{\partial \phi}{\partial x} = 0$ \Rightarrow Apply \Rightarrow $\frac{dx}{dt} = U/1 \Rightarrow x = Ut + (\xi)$
 $(-\infty < x < \infty)$ $\frac{d\phi}{dt} = 0 \Rightarrow \phi = F(\xi)$ constants



same for (x, t)

$\therefore F$ only depends on ξ .

$F(\xi(x, t=0)) = F(x - Ut) = e^{-x^2}$

Initial condition

② $\frac{\partial u}{\partial t} - \frac{1}{2} \frac{\partial u}{\partial x} = 0$ and $u(x, t=0) = e^{-x^2}$

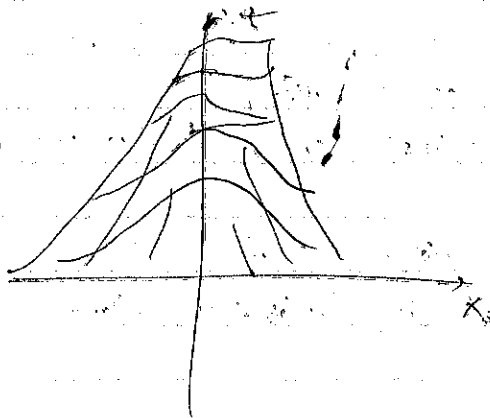
on characteristics, $\frac{dx}{dt} \Big|_{\xi} = -\frac{x}{2}$ and $\frac{du}{dt} \Big|_{\xi} = 0$

(1) $\Rightarrow \frac{1}{x} dx = -\frac{1}{2} dt \Rightarrow \ln(x) = -\frac{1}{2}t + c$

$\Rightarrow x = e^c \cdot e^{-1/2 \cdot t} = \xi e^{-t/2}$

(2) $\Rightarrow u = F(\xi) \text{ (constant)} = F(x \cdot e^{t/2})$

$u(x, t=0) = F(x) = e^{-x^2} \Rightarrow u = e^{-\xi^2}$



Example 3) $\frac{\partial u}{\partial t} + t \frac{\partial u}{\partial x} = 0$ $u(x, t=0) = e^{-x^2}$

Example 4) $\frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} = u$ $u(x, t=0) = e^{-x^2}$ (linear) (homogeneous)

⇒ Along characteristics, $\left. \frac{dx}{dt} \right|_z = 1$ and $\left. \frac{du}{dt} \right|_z = -u$

⇒ $x = t + c = t + z$ (∵ At time = 0 we want z)

⇒ $u = A e^{-t} = u_0 e^{-t} = u_0(z) e^{-t}$

$u(x, t=0) = u_0(z) = e^{-x^2} = e^{-z^2}$

⇒ $u = e^{-z^2} e^{-t}$ and $x = t + z$

⇒ $u(x, t) = e^{-(x-t)^2} e^{-t}$

Example 5) - Burgers' equation

$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = 0$ $u(x, t=0) = e^{-x^2}$ $u(x(t), t)$

Along characteristics, $\left. \frac{dx}{dt} \right|_z = u$ $\left. \frac{du}{dt} \right|_z = 0$

⇒ $u = F(z)$ u is independent of time

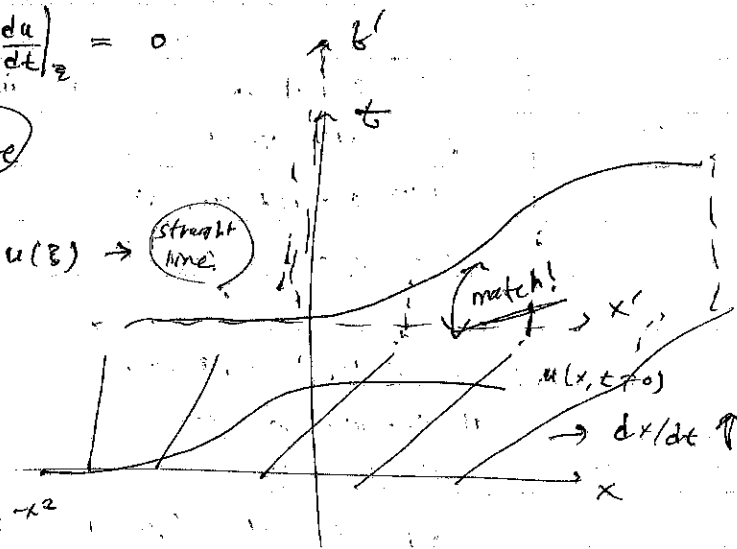
slope of characteristics doesn't change. $u(z) \rightarrow$ straight line

$x = ut + z = F(z)t + z$

$u = F(x - ut) \Big|_{t=0} = F(x) = e^{-x^2}$

⇒ $u = e^{-(x-ut)^2}$

implies solution



$$k_4 = 2.63 e^5$$

$$k_5 = 3.37 e^{-1}$$

Some Notes.

① Linearity - only talks about (y) respects to (x)

$$\text{E.g. } y'' + xy + x^3y = x^5 \rightarrow \text{Linear. (y respects)}$$

② Homogeneity $\rightarrow Qy'' + Qy = 0$

if it can be written as

$$\sum a_n(x) y^{(n)} = f(x) = 0 \rightarrow \text{Homogeneous}$$

* Exact equations

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0$$

$$\psi(x, y) \rightarrow \frac{\partial \psi}{\partial x} = M = \psi_x \Rightarrow \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y} \frac{dy}{dx} = 0 \rightarrow \psi(x, y) = 0$$
$$\frac{\partial \psi}{\partial y} = N = \psi_y$$

$$\frac{d\psi}{dx}$$

$$\Rightarrow M_y = N_x \Rightarrow \psi = \int M dx + \psi = \int N dy$$

$$\psi_{xy} = \psi_{yx}$$

③ 2nd order $ay'' + by' + cy = g(t)$

1) Constant coeff & linear $\rightarrow y = e^{rt} \Rightarrow (ar^2 + br + c)e^{rt} = 0$
characteristic equation.

(i) 2 real roots

$$y = c_1 e^{rt} + c_2 e^{st}$$

(ii) two complex conj roots ($r = \alpha \pm j\beta$)

$$y = e^{\alpha t} (c_1 \cos \beta t + c_2 \sin \beta t)$$

(iii) Repeated root (r)

$$y = a e^{rt} + c_2 t e^{rt}$$

$y = y_h + y_p \rightarrow$ particular

① Undetermined coeffs.

$$y'' - y = 3t^2 + t + 1$$

$$y_p = at^2 + bt + c \text{ (guess)}$$

② Variation of parameters.

$$y_p = u_1 y_1 + u_2 y_2$$

$$u_1 = - \int \frac{y_2 g(t)}{W(y_1, y_2)} dt$$

$$u_2 = \int \frac{y_1 g(t)}{W(y_1, y_2)} dt$$

$$W = y_1 y_2' - y_2 y_1'$$

Homogeneous

Inhomogeneous

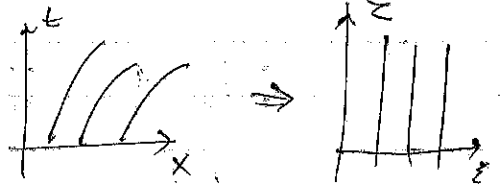
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PDE - characteristics, curv, shocks,

$$A(\varphi, x, t) \frac{\partial \varphi}{\partial t} + B(\varphi, x, t) \frac{\partial \varphi}{\partial x} + \tilde{c}(\varphi, x, t) = 0 \quad (*)$$

$$\tilde{c}(\varphi, x, t) = c(\varphi, x, t) + p(x, t)$$

$$(x, t) \rightarrow (\tilde{z}(x, t), \tau(x, t))$$



$$\begin{aligned} \frac{\partial \varphi}{\partial t} &= \frac{\partial \varphi}{\partial \tau} \frac{\partial \tau}{\partial t} + \frac{\partial \varphi}{\partial z} \frac{\partial z}{\partial t} \\ \frac{\partial \varphi}{\partial x} &= \frac{\partial \varphi}{\partial \tau} \frac{\partial \tau}{\partial x} + \frac{\partial \varphi}{\partial z} \frac{\partial z}{\partial x} \end{aligned}$$

$$\Rightarrow (*) \text{ becomes } \left(A \frac{\partial \tau}{\partial t} + B \frac{\partial \tau}{\partial x} \right) \frac{\partial \varphi}{\partial \tau} + \left(A \frac{\partial z}{\partial t} + B \frac{\partial z}{\partial x} \right) \frac{\partial \varphi}{\partial z} = 0$$

Need PDE \rightarrow ODE along $\tilde{z}(x, t)$.

Good choice!

$\tau = t$ \rightarrow This will work for most cases.

$$\Rightarrow A \frac{\partial \varphi}{\partial \tau} + \underbrace{\left(A \frac{\partial z}{\partial t} + B \frac{\partial z}{\partial x} \right)}_{=0} \frac{\partial \varphi}{\partial z} = -\tilde{c}$$

We want $\frac{\partial z}{\partial t} = 0 = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial t} = 0 \Rightarrow \frac{\partial z}{\partial t} = - \frac{dx}{dt} \frac{\partial z}{\partial x}$

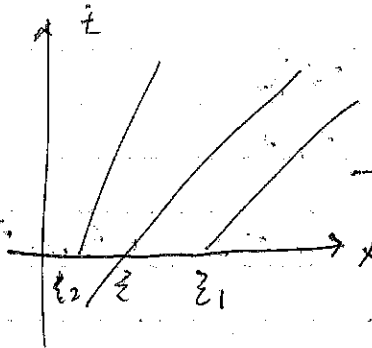
Along characteristic, $A \left(- \frac{dx}{dt} \Big|_z \frac{\partial z}{\partial x} \right) + B \left(\frac{\partial z}{\partial t} \right) = \frac{\partial z}{\partial x} \left(-A \frac{dx}{dt} \Big|_z + B \right)$

$$\Rightarrow \frac{dx}{dt} \Big|_z = \frac{B}{A} \quad \text{and} \quad \frac{\partial \varphi}{\partial \tau} \Big|_z = - \frac{\tilde{c}}{A}$$

Burger's equation:

1st order, Non linear PDE ; $\frac{\partial x}{\partial t} + u \frac{\partial u}{\partial x} = 0$

$\left. \frac{dx}{dt} \right|_{\xi} = u$, $\left. \frac{du}{dt} \right|_{\xi} = 0 \Rightarrow u(x,t) = G(\xi) \Rightarrow$ character are straight lines
 $\left. \frac{dx}{dt} \right|_{\xi} = \text{const}$



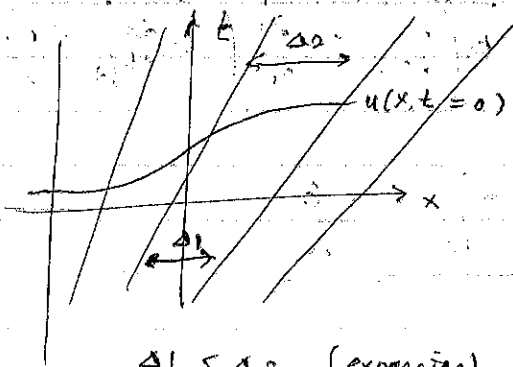
$x = G(\xi)t + \xi$

$\xi = x - G(\xi)t$

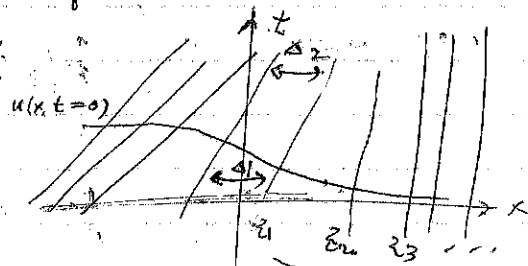
Impose initial condition : $u(x,t=0) = G(x - G(\xi)t) = G(x) = F(x)$

Solution : $u(x,t) = F(\xi) = F(x - ut)$
 \equiv implicit equation for u .

Expansion / Compression waves (Burger's equation).



$\Delta_1 < \Delta_2$ (expansion)



$\Delta_1 > \Delta_2$ (compression)

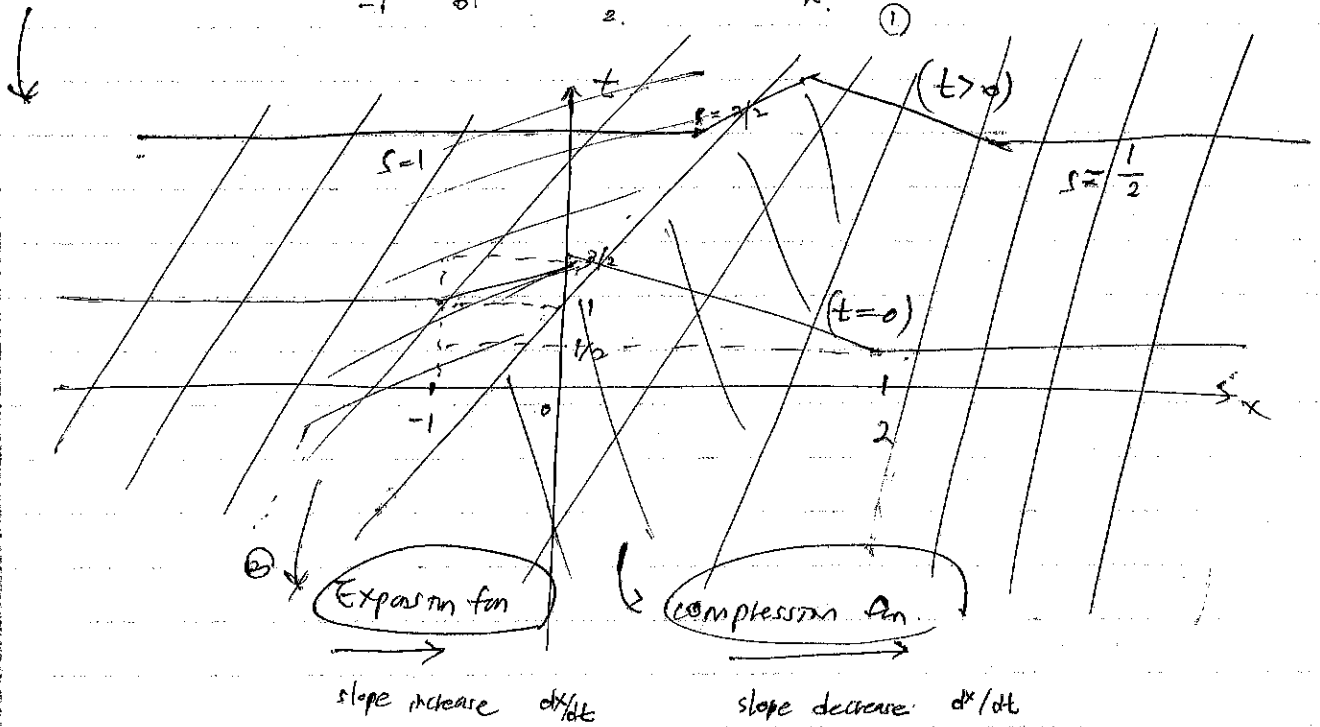
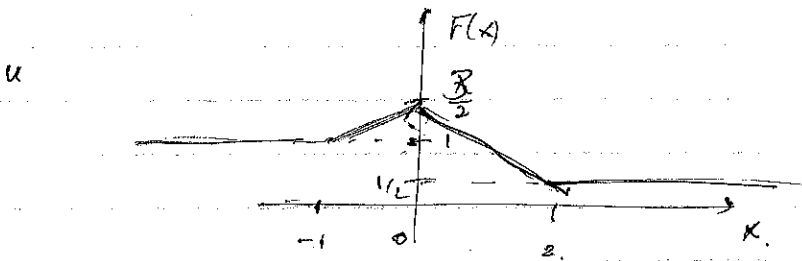
These don't change!

~~$u(x,t)$~~

Example

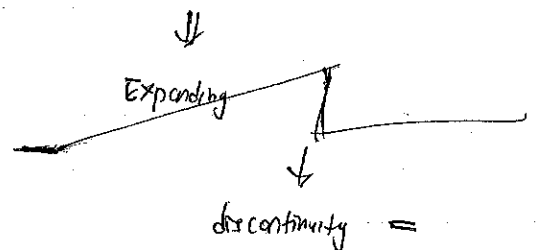
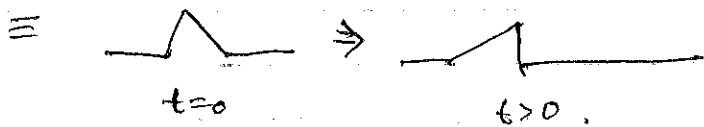
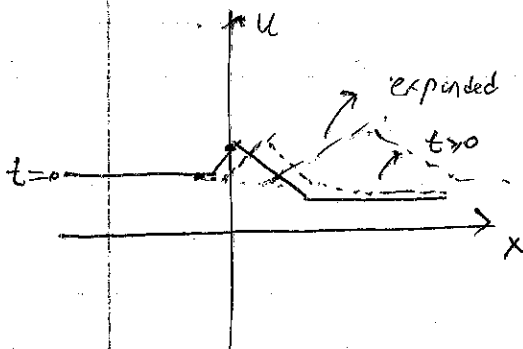
$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = 0$$

$$u(x, t=0) = F(x) = \begin{cases} 1 & x < -1 \\ \frac{x}{2} + \frac{3}{4} & -1 \leq x < 0 \\ \frac{3}{2} - \frac{x}{2} & 0 \leq x < 2 \\ \frac{1}{2} & 2 \leq x < \infty \end{cases}$$



- ① converges to a point. $\rightarrow t > 0$ (shock happens)
- ② converges to a point. $\rightarrow t < 0$

$t =$ shock formation time.



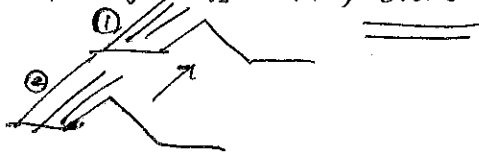
It is important that

ξ is invariant
respect to t

Characteristic equations are
drawn for $t=0$



It changes as $u(x,t)$ evolves



① & ② are different!

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Ph #3 → start from $(n=1)$

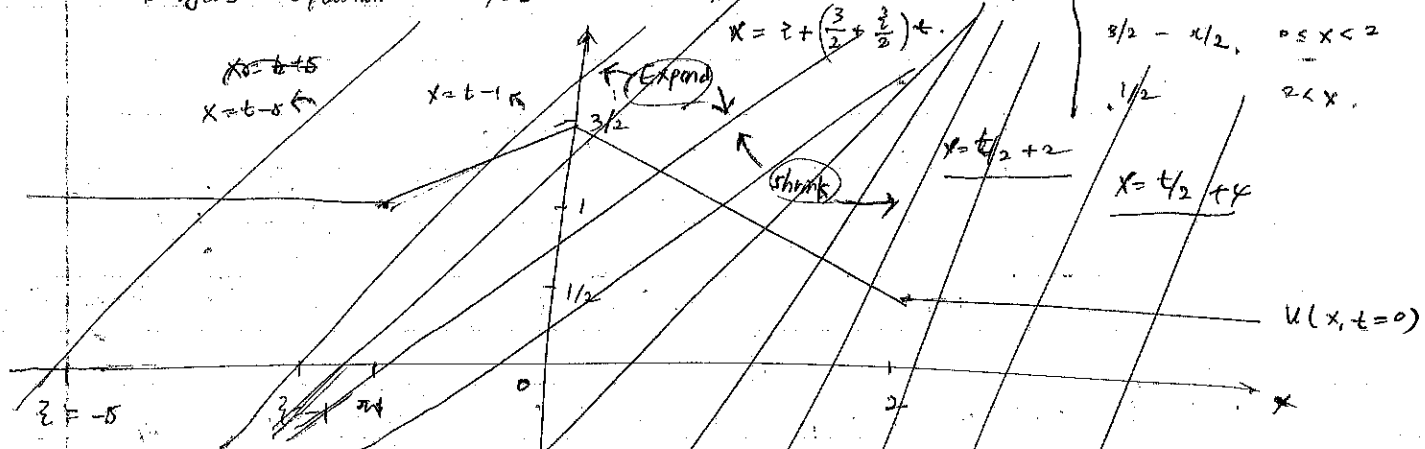
Lecture 4: shocks.

→ Burger's equation

$$u \frac{du}{dt} + u \frac{du}{dx} = 0$$

$$u(x, t=0) = u_0(x)$$

$$u_0(x) = \begin{cases} 1 & x < -1 \\ 3/2 + x/2 & -1 \leq x < 0 \\ 3/2 - x/2 & 0 \leq x < 2 \\ 1/2 & x \geq 2 \end{cases}$$



Characteristics $\rightarrow \frac{dx}{dt} \Big|_{\xi} = u \rightarrow x = u(\xi) \cdot t + \xi \rightarrow \xi = x - u(\xi) \cdot t$

$$\frac{du}{dt} \Big|_{\xi} = 0 \Rightarrow u = F(\xi) = u_0(\xi) = u_0(x - u(\xi)t)$$

$$u(x, t=0) = F(\xi(x, t=0)) \Rightarrow F(x) = u_0(x)$$

Note that this is $u_0(\xi)$ not $u(\xi)$ $\Rightarrow F(\xi) = u_0(\xi)$

- (i) $\xi < -1 \quad u_0(\xi) = 1 \Rightarrow x = t + \xi$
- (ii) $\xi \geq 2 \quad u_0(\xi) = 1/2 \Rightarrow x = t/2 + \xi$
- (iii) $-1 \leq \xi < 0 \quad u_0(\xi) = 3/2 + \xi/2 \Rightarrow x = \xi + u_0(\xi)t = \xi + \left(\frac{3}{2} + \frac{\xi}{2}\right)t$
- (iv) $0 \leq \xi < 2 \quad u_0(\xi) = 3/2 - \xi/2 \Rightarrow x = \xi + u_0(\xi)t = \xi + \left(\frac{3}{2} - \frac{\xi}{2}\right)t$

(iii) Expansion zone $-1 \leq \xi < 0 \Rightarrow t-1 \leq x < \frac{3}{2}t$

$$u(x, t) = u_0(\xi) = \frac{3}{2} + \frac{x/2}{1+t/2} - \frac{3}{2} \frac{t/2}{1+t/2}$$

(iv) shock zone $0 \leq \xi < 2 \Rightarrow 3/2t \leq x < t/2$

$$u(x, t) = \frac{x - 3/2t}{1 - t/2}$$

what if $t=2$?

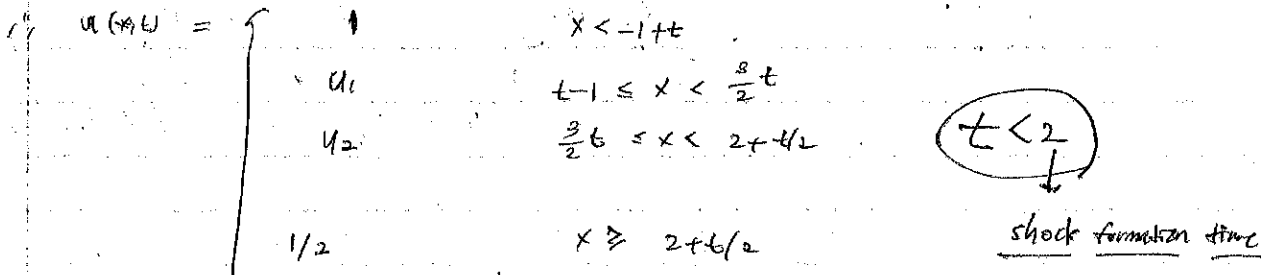
At $t=2 \rightarrow x = \xi(1 - t/2) + \frac{3}{2}t = \frac{3}{2}t$

$u =$

→ continued

At singular point, $u(x,t) = u_0(z) = (3/2 - z/2)t + z$
 $= 3/2 - \frac{x - 3/2 t}{2 - t} = \frac{3}{2} - \frac{x}{2-t} + \frac{3/2 t}{2-t}$

$x=3, t=2 \rightarrow u(x,t)$ has multiple values??



Shock formation time, $\frac{du}{dx}(x=3, t=2) = \infty$ idea \rightarrow applicable condition!

\rightarrow when $\frac{du}{dx}$ blows up, $u(x,t) = F(x - u(x,t), t)$

$\Rightarrow \frac{du}{dx} = \frac{\partial F}{\partial z} \frac{\partial z}{\partial x} = \frac{\partial F}{\partial z} (1 - \frac{du}{dx} \cdot t)$

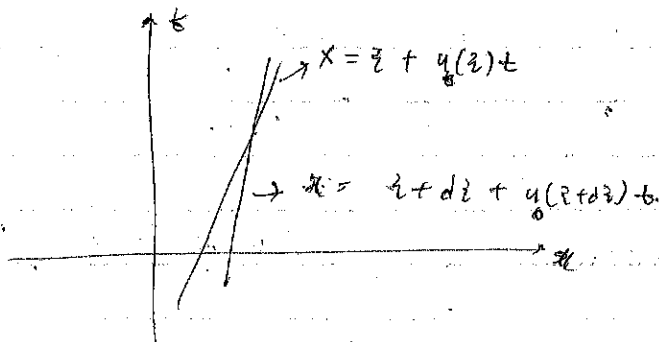
$\Rightarrow (1 + \frac{\partial F}{\partial z} t) \frac{du}{dx} = \frac{\partial F}{\partial z} \Rightarrow \frac{du}{dx} = \frac{\frac{\partial F}{\partial z}}{1 + t \cdot \frac{\partial F}{\partial z}}$

$\Rightarrow t_{shock} = -\frac{1}{\frac{\partial F}{\partial z}}$ (assume F is smooth function)

$t_s = \min_z \left(-\frac{1}{\frac{\partial F}{\partial z}} \right)$

x formal way
 $x = u_0(z)t + z$
 $\frac{dx}{dz} \Big|_{t=t_s} = 0$ (x doesn't change w.r.t. z)
 $z, z+dz, z+2dz, \dots \rightarrow$ don't change

Shock formation time (geometric interpretation)



\rightarrow Intersection
 $\Rightarrow dz + \frac{t}{2} (u_0(z+dz) - u_0(z)) = 0$

$\Rightarrow t_s = \frac{1}{\frac{u_0(z+dz) - u_0(z)}{dz}}$

$u_0 \rightarrow$ smooth $\rightarrow t_{shock} = \frac{-1}{\frac{\partial u_0}{\partial z}}$

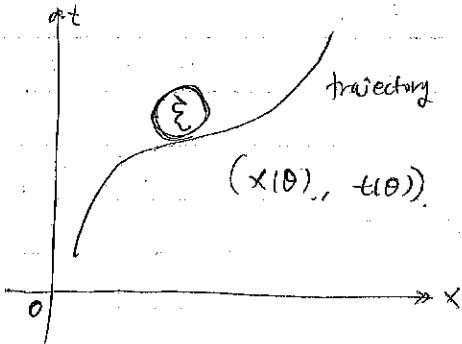
TA session

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- 1st order PDEs.

$$\partial\phi/\partial t + u(\phi, x, t) \partial\phi/\partial x = S(\phi, x, t) \quad \text{--- (1)}$$

$x \in \mathbb{R} \quad t \in \mathbb{R} \quad t > 0.$
I. C. $\phi(x, t=0) = F(x).$



① $\left. \frac{dx}{dt} \right|_{\text{trajectory}} = u(\phi, x, t)$

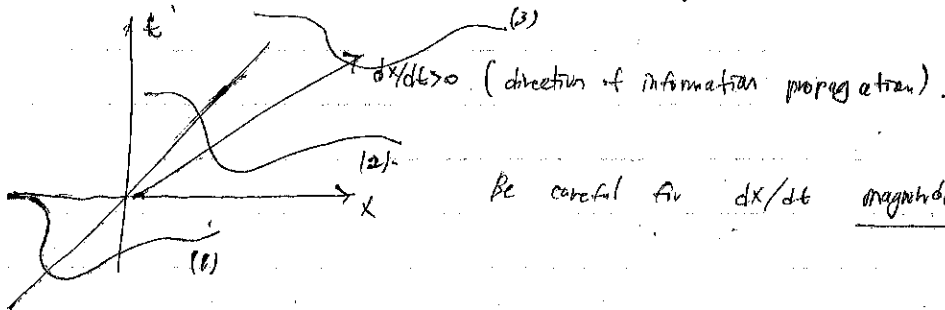
② $\left. \frac{d\phi}{dt} \right|_{\text{trajectory}} = S(\phi, x, t)$

$\therefore d(\cdot)/d\theta = \frac{dt}{d\theta} \partial/\partial t + \frac{dx}{d\theta} \partial/\partial x \rightarrow$ Apply to ①

$\hookrightarrow \boxed{\theta = t} \Rightarrow \left. \frac{d}{dt} \right|_{\text{trajectory}} = 1 \cdot \partial/\partial t + \left. \frac{dx}{dt} \right|_{\text{trajectory}} \cdot \partial/\partial x$

- Along the characteristics.

$\left. \frac{dx}{dt} \right|_{\xi} = u(\phi, x, t) \rightarrow$ propagation speed of equation (carry information).



- $dx/dt = kt = \text{constant} \rightarrow$ straight lines
- $dx/dt = u(\phi) \rightarrow$ not parallel but straight lines.

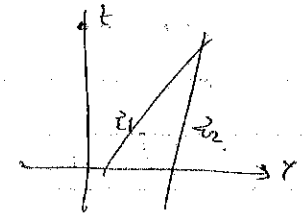
Ex. 1) $2xt \frac{\partial \phi}{\partial x} + (1+t^2) \left(\frac{\partial \phi}{\partial t} + \phi \right) = 0$

- Type. $\left\{ \begin{array}{l} \rightarrow \text{First order in } x \text{ and } t. \\ \rightarrow \text{Homogeneous (} \phi=0 \text{ satisfies given PDE)} \\ \rightarrow \text{Linear equation. (} \therefore \text{ No } \phi, d\phi \text{ terms)} \rightarrow \text{No shock!} \\ \rightarrow \text{Variable coefficient.} \end{array} \right.$

$\Rightarrow \frac{\partial \phi}{\partial t} + \frac{2t^2}{1+t^2} x \frac{\partial \phi}{\partial x} = -\phi$
 $\boxed{u(x,t)}$

$\phi(x, t=0) = \tanh(x)$

$\left. \frac{dx}{dt} \right|_{z_1} \neq \left. \frac{dx}{dt} \right|_{z_2} \rightarrow \text{shock happens}$



But, $\left. \frac{dx}{dt} \right|_{z_1} = \left. \frac{dx}{dt} \right|_{z_2} = u(x,t) \rightarrow \text{uniquely defined.}$

$\frac{dx}{dt} = \frac{2t}{1+t^2} x \Rightarrow x = z(1+t^2)$

$\frac{d\phi}{dt} = -\phi \Rightarrow \phi = \underbrace{\phi(z,0)}_{\text{on the trajectory}} \exp(-t) = \tanh(z) \exp(-t)$

$\frac{x}{1+t^2}$

Ex. 2) $\frac{\partial u}{\partial t} + u^2 \frac{\partial u}{\partial x} = \beta u$ ($\beta > 0$)

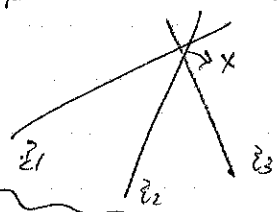
$\Rightarrow \frac{dx}{dt} = u^2 \quad \frac{du}{dt} = \beta u > 0$
 ↓ characteristics ↓

~~$x = u^2 t + z$~~ $u = F(z) \cdot \exp(\beta t)$ (3)

$\frac{dx}{dt} = (F(z))^2 \exp(2\beta t) \Rightarrow \int_z^x dx = \int_0^t (F(z))^2 \exp(2\beta \tau) d\tau$ (z marks where $t=0$)

$\Rightarrow x = \frac{(F(z))^2 \exp(2\beta t)}{2\beta} - \frac{(F(z))^2}{2\beta} + z$

↳ shock? $\rightarrow \frac{dx}{dz} = 0$



$\rightarrow (x \text{ shouldn't change for different trajectories.})$

I.C: $u(x, t=0) = \exp(-x^2)$

$\Rightarrow \textcircled{3}: u(t) = F(z) \cdot 1 = \exp(-z^2) \quad F(x) = e^{-x^2}$

$\rightarrow \text{Continue}$

$$t_s = \frac{1}{2\beta} \ln \left(1 + \frac{\beta \exp(2z^2)}{2z} \right) \rightarrow \text{multiple } t_s \text{ for } z \text{ values}$$

$$\rightarrow t_s = \min(t_s) \Rightarrow \frac{dt_s}{dz} = 0 \rightarrow \text{? (can you guarantee it's a minimum?)}$$

$$\hookrightarrow t_s = \frac{1}{2\beta} \ln(1 + \beta z) \Rightarrow A)$$

* In $\beta = 0$ case, $u = F(z) \rightarrow \dots$

$$x = (\exp(-2z^2))^2 + z \rightarrow \text{shock is possible}$$

$$\textcircled{1} \quad \frac{dx}{ds} = \frac{B}{A} \frac{dt}{ds}$$

$$\text{for } A(\phi, x, t) \frac{\partial \phi}{\partial t} + B(\phi, x, t) \frac{\partial \phi}{\partial x} + C(\phi, x, t) + D(x, t) = 0$$

$$\textcircled{2} \quad \frac{d\phi}{ds} = - \frac{C(\phi, x, t) + D(x, t)}{A(\phi, x, t)} \frac{dt}{ds}$$

< Confusion in concepts \rightarrow Eliminated >

Let's say we have $u_t + 2tx^2 u_x = 0$ $u(x, t=0) = \exp(-x^2)$

$$\text{characteristic curve } (x(\theta), t(\theta)) \Rightarrow \left. \frac{dx}{d\theta} \right|_z = 2tx^2 \frac{dt}{d\theta} \quad \text{--- } \textcircled{1}$$

which means that on z (trajectory), $\textcircled{1}$ holds.

\rightarrow we take $s = \theta = t$ (for convenience only)

$$\Rightarrow \left. \frac{dx}{dt} \right|_z = 2tx^2 \cdot 1 \Rightarrow \frac{dx}{x^2} = 2tdt \quad \left|_z \Rightarrow -\frac{1}{x} = t^2 + z\right.$$

$$\text{since we have } -\frac{1}{x} = t^2 + z \quad \text{--- } \textcircled{2}$$

\rightarrow we have $\left. \frac{du}{dt} \right|_z = 0$ on trajectory $\Rightarrow u = F(z)$ trajectory

"shouldn't change along characteristic" line.

\rightarrow changes respect to different z

$$\Rightarrow u = F(z) = F\left(-\frac{1}{x} - t^2\right)$$

$$u_0(x) = F\left(-\frac{1}{x} - 0^2\right) = F\left(-\frac{1}{x}\right) = \exp(-x^2)$$

$$\Rightarrow F(z) = \exp\left(-\left(-1/z\right)^2\right) = \exp\left(-\frac{1}{z^2}\right)$$

$$\Rightarrow u = \exp\left(-\frac{1}{\left(\frac{1}{x} + t^2\right)^2}\right)$$

2) what if, we take $-\frac{1}{x} + z = t^2$ $\text{--- } \textcircled{3} \Rightarrow z = \frac{1}{x} + t^2$

$$u_0(x) = F\left(\frac{1}{x}\right) = \exp(-x^2) \Rightarrow F(z) = \exp\left(-\frac{1}{z^2}\right)$$

$$\Rightarrow u = \exp\left(-\frac{1}{\left(\frac{1}{x} + t^2\right)^2}\right)$$

2), 3) are same!

01/23/2024

Lecture 5: Wrapping up Characteristic Methods (1st order PDE)

$$\phi(x,t) \Rightarrow A \frac{\partial \phi}{\partial t} + B \frac{\partial \phi}{\partial x} + \tilde{C} = 0.$$

$$\Rightarrow \boxed{\frac{dt}{A} = \frac{dx}{B} = \frac{d\phi}{-\tilde{C}}}$$

Example:

$$\frac{A}{A} \frac{\partial \phi}{\partial t} + \frac{B}{A} \frac{\partial \phi}{\partial x} + \frac{C}{A} \frac{\partial \phi}{\partial y} + \frac{D}{A} \frac{\partial \phi}{\partial z} + \frac{\tilde{E}}{A} = 0 \quad (\phi(x,y,z,t)) \quad \text{--- 1}$$

$$\Rightarrow \left. \frac{d\phi}{dt} \right|_z = \frac{\partial \phi}{\partial t} + \left. \frac{dx}{dt} \right|_z \frac{\partial \phi}{\partial x} + \left. \frac{dy}{dt} \right|_z \frac{\partial \phi}{\partial y} + \left. \frac{dz}{dt} \right|_z \frac{\partial \phi}{\partial z} \quad \text{--- 2}$$

(on the characteristics).

Comparing 1 and 2, $\left. \frac{dx}{dt} \right|_z = B/A$, $\left. \frac{dy}{dt} \right|_z = C/A$, $\left. \frac{dz}{dt} \right|_z = D/A$.

Alternatively, $\boxed{\frac{dx}{B} = \frac{dy}{C} = \frac{dz}{D} = \frac{d\phi}{-\tilde{E}}} = \frac{dt}{A}$



• Conservation laws.

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \nabla \vec{u} = 0 \quad (\text{primitive form})$$

$$\frac{\partial u}{\partial t} + \frac{d}{dx} \left(\frac{\vec{u}^2}{2} \right) = 0 \quad (\text{conservative form})$$

Flux term.

General law: $\frac{\partial u}{\partial t} + \frac{\partial}{\partial x} F(u, x, t) = 0$

→ Conservation laws in integral form always hold

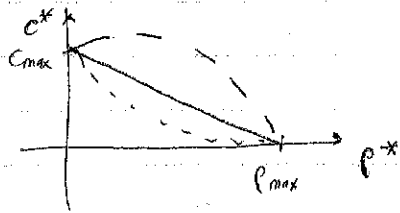
Ex. $\frac{\partial \rho^*}{\partial t} + \frac{\partial F^*}{\partial x} = 0$ (car flow model)

$$\downarrow F^*(\rho^*) = \rho^* c(\rho^*) \rightarrow \frac{\partial \rho^*}{\partial t} + \left(\frac{\partial c}{\partial \rho^*} \rho^* + c \right) \frac{\partial \rho^*}{\partial x} = 0.$$

$$\Rightarrow \left. \frac{dx}{dt} \right|_z = \frac{dc^*}{d\rho^*} \rho^* + c^* \rightarrow g(\rho^*)$$

$$\left. \frac{d\rho^*}{dt} \right|_z = 0 \quad \rho^* \rightarrow \text{constant}$$

Let's use model of



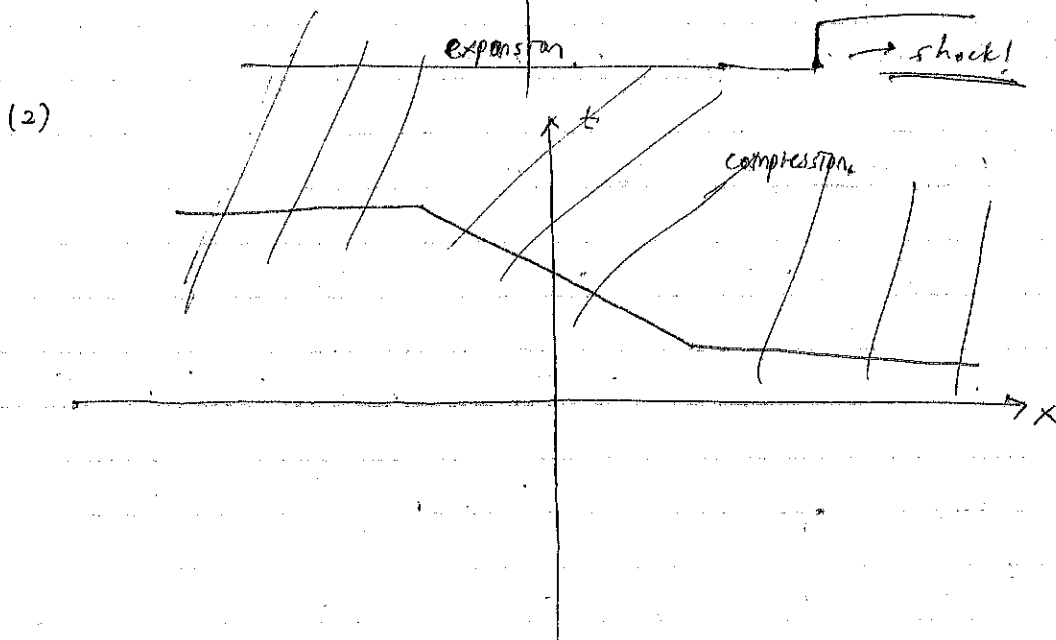
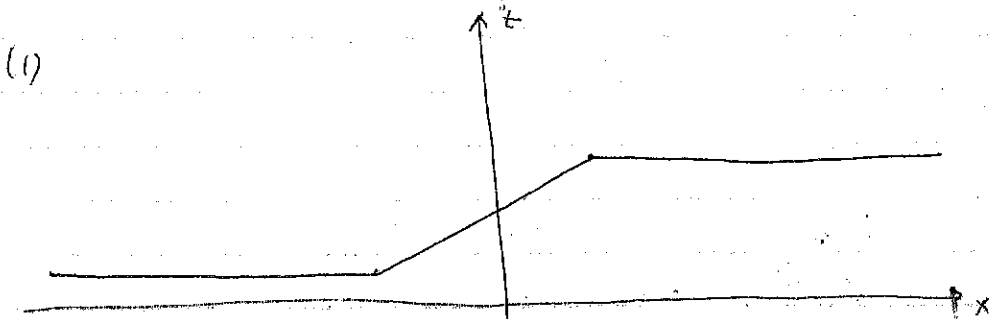
$$p = p^*/p_{max}$$

$$c = c^*/c_{max} \Rightarrow c(p) = 1-p$$

$$c^* = c_{max} (1 - p^*/p_{max})$$

$$\Rightarrow \frac{\partial p}{\partial t} + \frac{\partial}{\partial x} (pc(p)) = 0 \Rightarrow \frac{\partial p}{\partial t} + (c+p \frac{\partial c}{\partial p}) \frac{\partial p}{\partial x} = 0$$

$$\Rightarrow \frac{\partial p}{\partial t} + (1-2p) \frac{\partial p}{\partial x} = 0 \Rightarrow \begin{cases} dx/dt|_2 = 1-2p \\ dc/dt|_{sh} = 0 \end{cases}$$



Weak solution = smooth + countable jumps.

Let's find "shock speed" → solution in differentiable parts,
jump across shock.

Concentrate on one shock: $X_s(t)$

coordinate change: $z = x - X_s(t)$

$p(x, t) \rightarrow p(z, \tau)$

$\tau = t$

↑
Riding the shock

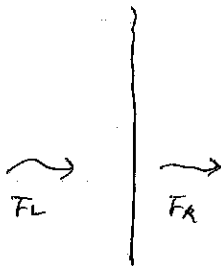
$$\frac{\partial p}{\partial t} + \frac{\partial}{\partial x}(pc) = 0 \rightarrow \frac{\partial p}{\partial \tau} + \frac{\partial}{\partial z}(pc - pX_s) = 0.$$

Inside the car, shock transition is very smooth,

But outside the car, as x evolves, there exists a sudden shock location.

< At frame of reference of shock >

Property of conservation: $F_L = F_R$ Hydrostatic condition

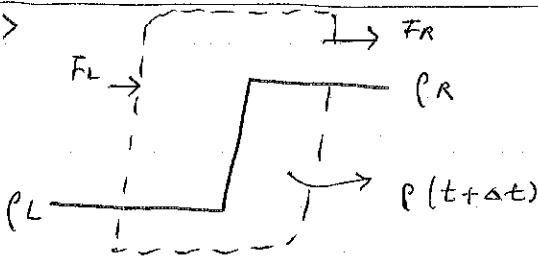


$$p_L c_L(p) = p_R c_R(p) \Rightarrow \dot{X}_s = \frac{p_R c_R(p_R) - p_L c_L(p_L)}{p_R - p_L}$$

< at general frame >

In general, $\dot{X}_s = \frac{F_R - F_L}{p_R - p_L}$
 ↑ fluxes
 ↓ state variables.

< Intuition >

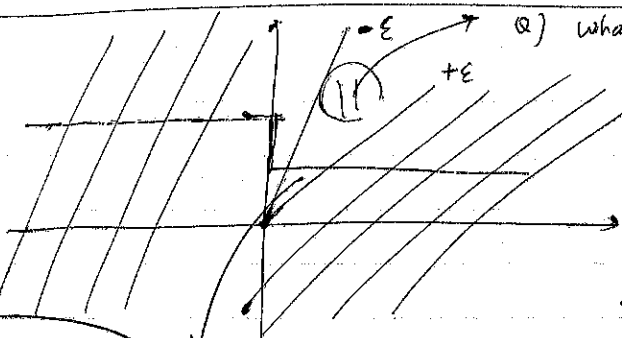


$$\int_{x_0}^{x_0 + X_s \Delta t} p(t + \Delta t) dx - \int_{x_0}^{x_0} p(t) dx = \dot{X}_s \Delta t (p_R - p_L)$$

Integral of fluxes

// in time domain

$$(F_L - F_R) \Delta t$$



Q) what happens here?

$$\left. \begin{aligned} \frac{dx}{dt} \Big|_z &= 1 - 2p \\ \frac{dp}{dt} \Big|_z &= 0 \end{aligned} \right\} \Rightarrow \text{Straight Characteristic Lines.}$$

is absolute.

→ (x, t) : slope = x/t (∵ passes through origin) = $1 - 2p$ $\Rightarrow p = \frac{1 - x/t}{2}$

Centered expansion fan

circled scribble

01/25/2024

Lecture 6. (ch3)

Second order PDE. (ex. wave equation)

$$\frac{\partial^2 u}{\partial t^2} - c_0^2 \frac{\partial^2 u}{\partial x^2} = 0 \quad (\text{we need two } (b, c), \text{ two } (init. cond.))$$

↳ D'Alembert soln.

$$\left. \begin{aligned} u(x, t=0) &= f(x) \\ \frac{\partial u(x, t=0)}{\partial t} &= g(x) \end{aligned} \right\} \Rightarrow u(x, t) = \frac{1}{2} \{ f(x-ct) + f(x+ct) \} + \frac{1}{2c_0} \int_{x-ct}^{x+ct} g(x') dx' \quad \text{--- (1)}$$

(Note: $\frac{\partial^2 u}{\partial t^2} - c_0^2 \nabla^2 u = 0$
Linear PDE \rightarrow Transformation method
Eigenfunction expansions)

Proof of (1) Method of characteristics after convert to 1st order PDEs.

Approach: 1) Rewrite system into coupled 1st-order PDEs.

2) Decouple them!

3) Solve individually.

4) Construct back solution for original PDE.

• $u_1 = \frac{\partial u}{\partial x} \quad u_2 = \frac{\partial u}{\partial t}$

$$\vec{u} = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} \Rightarrow \begin{aligned} \frac{\partial}{\partial t} \left(\frac{\partial u}{\partial t} \right) - c_0^2 \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} \right) &= 0 \\ \Rightarrow \frac{\partial u_2}{\partial t} - c_0^2 \frac{\partial u_1}{\partial x} &= 0 \end{aligned} \quad \text{--- (1)}$$

$$\frac{\partial u_1}{\partial t} = \frac{\partial}{\partial t} \left(\frac{\partial u}{\partial x} \right) = \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial t} \right) = \frac{\partial}{\partial x} u_2 \quad \text{--- (2)}$$

(1), (2) becomes

$$\begin{aligned} \frac{\partial u_1}{\partial t} - \frac{\partial u_2}{\partial x} &= 0 \\ \frac{\partial}{\partial t} (u_2) - \frac{\partial}{\partial x} (u_1) &= 0 \end{aligned} \Rightarrow \frac{\partial \vec{u}}{\partial t} + \begin{pmatrix} 0 & -1 \\ -c_0^2 & 0 \end{pmatrix} \frac{\partial \vec{u}}{\partial x} = \vec{0}$$

$$\Rightarrow \frac{d\vec{u}}{dt} + \begin{pmatrix} 0 & 1 \\ c_0^2 & 0 \end{pmatrix} \frac{d\vec{u}}{dx} = \vec{0}$$

↓ Diagonalization

$$\Rightarrow B \Rightarrow \text{Eig. vals, decomp.} : \begin{pmatrix} 1 \\ -c_0 \end{pmatrix} \text{ and } \begin{pmatrix} 1 \\ c_0 \end{pmatrix} \Rightarrow P = \begin{pmatrix} 1 & 1 \\ -c_0 & c_0 \end{pmatrix} \quad \Lambda = \begin{pmatrix} c_0 & 0 \\ 0 & -c_0 \end{pmatrix}$$

$$\Rightarrow B = Q \Lambda Q^{-1} \quad \text{whereas } \vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = Q^{-1} \vec{u} \quad (\text{we defined it!})$$

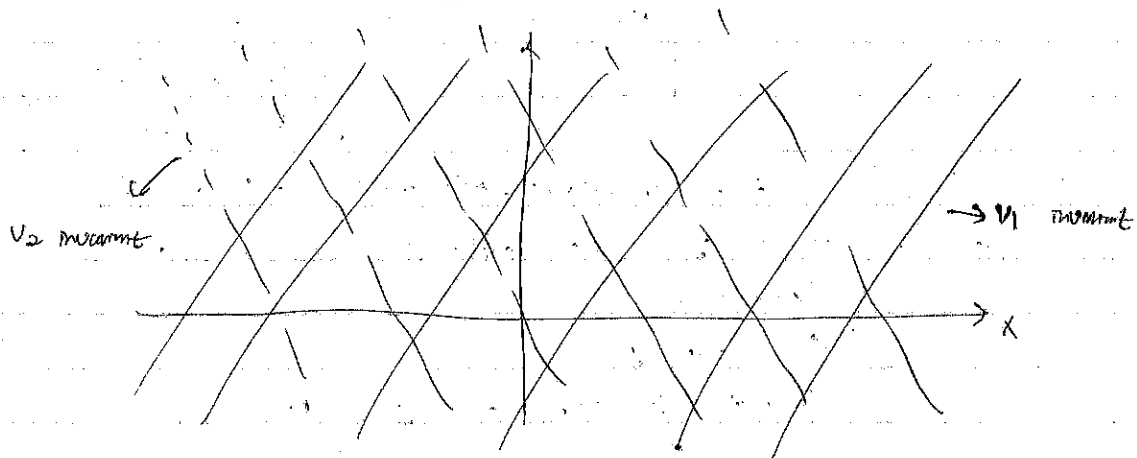
$$\frac{\partial \vec{u}}{\partial t} + Q \Lambda Q^{-1} \frac{\partial \vec{u}}{\partial x} = \vec{0} \Rightarrow Q^{-1} \frac{\partial \vec{u}}{\partial t} + \Lambda Q^{-1} \frac{\partial \vec{u}}{\partial x} = \vec{0}$$

$$\Rightarrow \frac{\partial \vec{v}}{\partial t} + \Lambda \frac{\partial \vec{v}}{\partial x} = \vec{0} \quad \rightarrow \text{Now it's decoupled!}$$

$$\Rightarrow \frac{\partial}{\partial t} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} + \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \frac{\partial}{\partial x} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \left. \begin{aligned} \frac{\partial v_1}{\partial t} + \lambda_1 \frac{\partial v_1}{\partial x} &= 0 \\ \frac{\partial v_2}{\partial t} + \lambda_2 \frac{\partial v_2}{\partial x} &= 0 \end{aligned} \right\}$$

Characteristic Variables
 < decoupled systems >



I.C. for v_1 and v_2 . $u(x, t=0) = f(x)$
 $\frac{\partial u(x, t=0)}{\partial t} = 0$

$$\textcircled{1} \left. \begin{aligned} v_1(x, t=0) &= f'(x)/2 \\ v_2(x, t=0) &= f'(x)/2 \end{aligned} \right\} \begin{aligned} v_1(x, t) &= F^+(x) = \frac{1}{2} f'(x-ct) \\ v_2(x, t) &= F^-(x) = \frac{1}{2} f'(x) \\ \checkmark v_1(x, t) &= \frac{1}{2} f'(x-ct) \end{aligned}$$

$$\begin{aligned} v_2(x, t) &= F^-(x+ct) \\ v_2(x, t=0) &= F^-(x) = \frac{1}{2} f'(x) \\ \checkmark v_2(x, t) &= \frac{1}{2} f'(x+ct) \end{aligned}$$

$$\textcircled{2} U = Q\vec{v} \Rightarrow \begin{aligned} u_1 &= v_1 + v_2 & u_1 &= \frac{1}{2} [f'(x-ct) + f'(x+ct)] \\ u_2 &= c(v_2 - v_1) & \parallel & \frac{du}{dx} \end{aligned}$$

$$\Rightarrow u = \int \frac{du}{dx} dx = \frac{1}{2} \{ f(x-ct) + f(x+ct) \} + I(t)$$

③ From ②, $u(x,t) = \frac{1}{2} \{ f(x-ct) + f(x+ct) \} + I(t)$.

We can use initial condition of $\partial u / \partial t (x, t=0)$.

$$u(x, t=0) = f(x) + I(0) = f(x) \Rightarrow I(0) = 0$$

$$\left. \frac{\partial u}{\partial t} (x,t) \right|_{t=0} = \frac{1}{2} \left\{ -c \cdot f(x-ct) + c \cdot f(x+ct) \right\} \Big|_{t=0} + \left. \frac{dI}{dt} \right|_{t=0}$$

$$\Rightarrow 0 = \frac{1}{2} \{ -c \cdot f(x) + c \cdot f(x) \} + \left. \frac{dI}{dt} \right|_{t=0} = 0 \quad \text{--- (5)}$$

Pach

But if we defined init. cond. to be $\partial u / \partial t (x, t=0) = g(x)$,

$$g(x) = \left. \frac{dI}{dt} \right|_{t=0} \text{ is satisfied.}$$

Let's talk about (5) case,

Plugging in $u = \frac{1}{2} \{ f(x-ct) + f(x+ct) \} + I$ to

$$\partial^2 u / \partial t^2 - c^2 \partial^2 u / \partial x^2 = 0$$

$$\Rightarrow 0 - 0 + I'' - c^2 I = 0 \Rightarrow I(0) = 0 \rightarrow I = 0$$

$$I'(0) = 0$$

$$I''(0) = 0$$

< Generalize >

$$\frac{\partial^2 u}{\partial x^2} + \frac{B}{A} \frac{\partial^2 u}{\partial x \partial y} + \frac{C}{A} \frac{\partial^2 u}{\partial y^2} = \frac{D}{A} \rightarrow u_1 = \partial u / \partial x, u_2 = \partial u / \partial y$$

$$\frac{\partial}{\partial x} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} + \begin{pmatrix} B/A & C/A \\ -1 & 0 \end{pmatrix} \frac{\partial}{\partial y} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} D/A \\ 0 \end{pmatrix}$$

$$\partial u_2 / \partial x = \partial u_1 / \partial y \quad (\text{2nd equation})$$

Can B matrix diagonalized \rightarrow if so, we can easily solve!

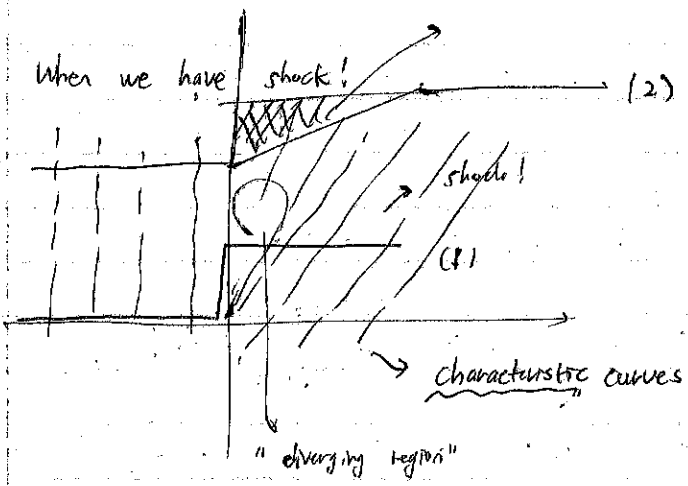
②) Determine diagonalizability.

$$\rightarrow |\lambda I - B| \Rightarrow \Delta = B^2 - 4AC \quad (i) > 0 \text{ hyperbolic (two distinct reals)}$$

$$(ii) = 0 \text{ parabolic (repeated)}$$

$$(iii) < 0 \text{ elliptic (two complex conjugates)}$$

GR



(1) becomes (evolves to) (2)

01/30/2024

Lecture 7. (Last lecture + method of characteristics)

- Wave eqn.

$$u(x,t) \text{ where } \{(x,t) \mid -\infty < x < \infty, 0 \leq t < \infty\}$$

$$u(x,t) \text{ satisfies } \frac{\partial^2 u}{\partial t^2} - c^2 \frac{\partial^2 u}{\partial x^2} = 0 \quad \left\{ \begin{array}{l} u(x,t=0) = f(x) \\ u'(x,t=0) = g(x) \end{array} \right.$$

$$\text{D'Alembert says: } u(x,t) = \frac{1}{2} \{ f(x-ct) + f(x+ct) \} + \frac{1}{2c} \int_{x-ct}^{x+ct} g(\tau) d\tau$$

\downarrow Right going wave \downarrow Left going wave

① New way to solve! \equiv operators!

$$\underbrace{\left(\frac{\partial}{\partial t} + c \frac{\partial}{\partial x} \right)}_{\text{Left}} \underbrace{\left(\frac{\partial}{\partial t} - c \frac{\partial}{\partial x} \right)}_{\text{Right}} u = 0 \quad \equiv \text{Double advection,} \\ \rightarrow \text{Advection operators.}$$

$$\begin{array}{l} \text{(i) } z^+ = x - ct \\ \text{(ii) } z^- = x + ct \end{array} \left\{ \begin{array}{l} \text{Trajectories where } \text{information is transferred.} \end{array} \right.$$

$$\text{Change (transform) } (x,t) \rightarrow (z^+, z^-) \Rightarrow \frac{\partial}{\partial z^+} \frac{\partial}{\partial z^-} u = 0 \Leftrightarrow u_{z^+ z^-} = 0$$

$$\Rightarrow \text{we know } u(z^+, z^-) = G^+(z^+) + G^-(z^-) \\ = G^+(x-ct) + G^-(x+ct)$$

$$\left. \begin{array}{l} \text{Using B.C. where } u(x,t=0) = G^+(x) + G^-(x) = f(x) \\ \frac{\partial}{\partial t} u(x,t=0) = -c G^+(x) + c G^-(x) = g(x) \end{array} \right\} \text{--- (*)}$$

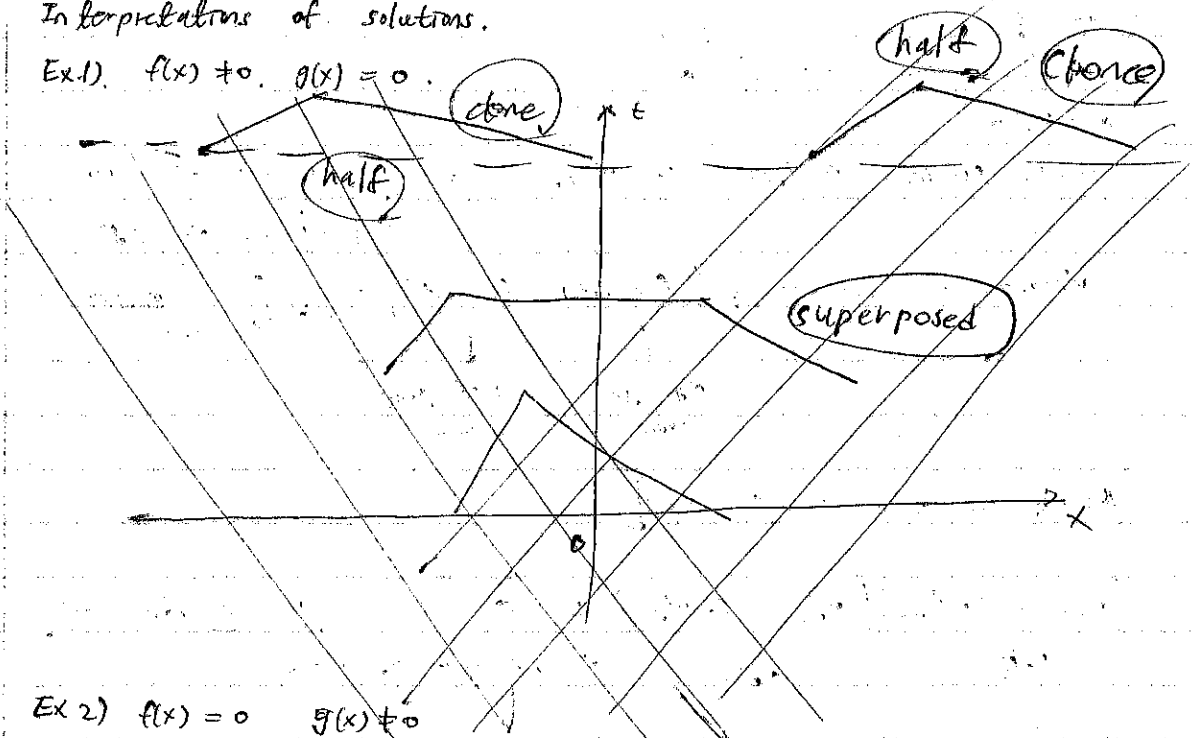
$$\begin{array}{l} (*) \text{ becomes, } G^+(x) + G^-(x) = f(x) \\ G^+(x) - G^-(x) = -\frac{1}{c} \int g(\tau) d\tau \end{array}$$

$$\Rightarrow G^+(x) = \frac{f(x) - \frac{1}{c} \int g(\tau) d\tau}{2} \quad \text{and} \quad G^-(x) = \frac{f(x) + \frac{1}{c} \int g(\tau) d\tau}{2}$$

$$\Rightarrow u = G^+(x-ct) + G^-(x+ct) = \frac{1}{2} \{ f(x-ct) + f(x+ct) \} + \frac{1}{2c} \int_{x-ct}^{x+ct} g(\tau) d\tau \quad \#$$

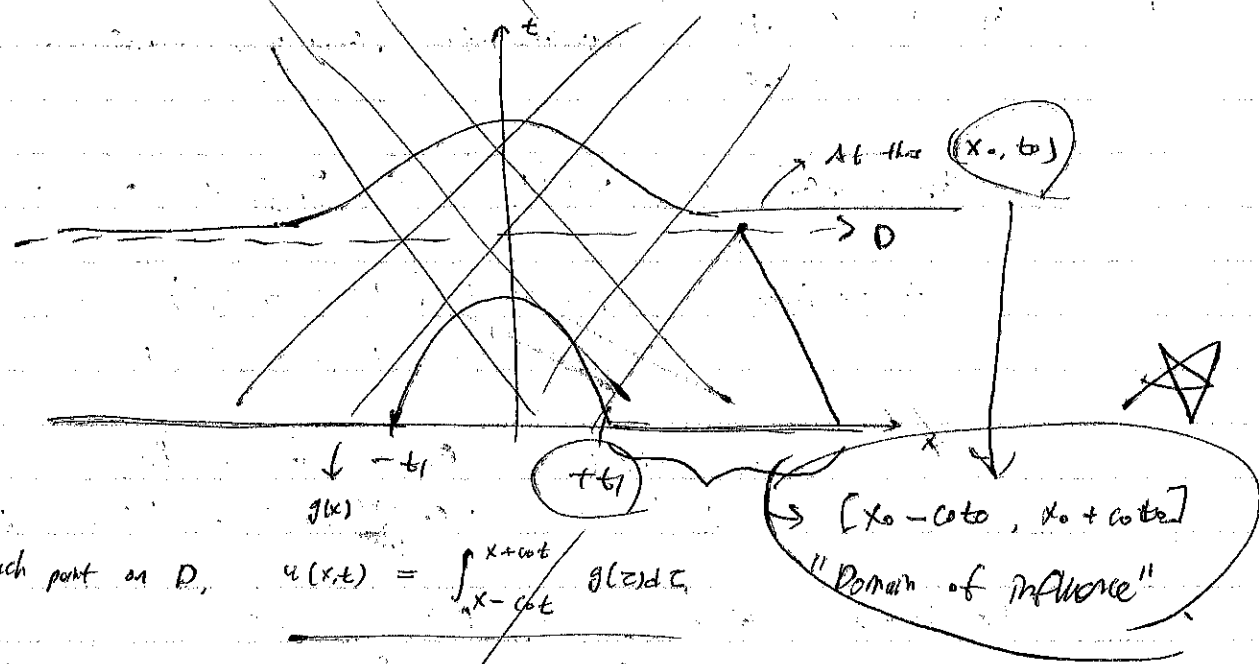
In interpretations of solutions.

Ex 1) $f(x) \neq 0, g(x) = 0$



Match!

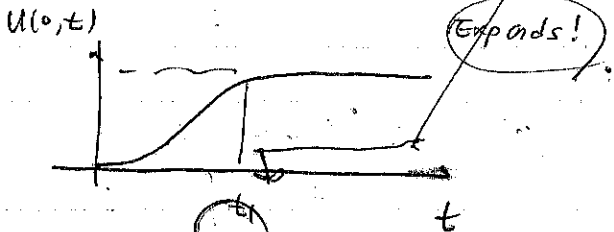
Ex 2) $f(x) = 0, g(x) \neq 0$



Each point on D,
$$u(x,t) = \int_{x-ct}^{x+ct} g(z) dz$$

As t grows, $[x-ct, x+ct]$ gets larger, thus

the shape \rightarrow \rightarrow \rightarrow



Example 3). One way waves. (wave absorbers, wave absorbers, b.c.s).

$u(x,t) = f(x - c_0 t)$ is a solution.

$\partial u / \partial t = -c_0 f'(x - c_0 t)$.

$\left\{ \begin{array}{l} \text{I.C. } u(x,0) = f(x) \\ u'(x,0) = -c_0 f'(x) \end{array} \right.$

$\vec{v}_1 = \frac{1}{2} \left(\frac{\partial u}{\partial x} - \frac{1}{c_0} \frac{\partial u}{\partial t} \right) = f'$

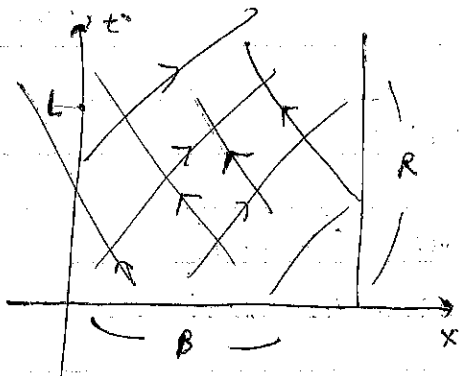
$\vec{v}_2 = \frac{1}{2} \left(\frac{\partial u}{\partial x} + \frac{1}{c_0} \frac{\partial u}{\partial t} \right) = 0$

$v_2 = 0$ at $t \geq 0$

↳ "carries no information"

Initial conditions & Boundary conditions.

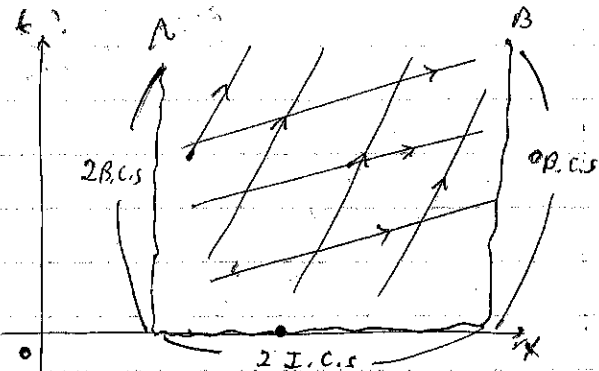
Q) Where? How many? What? → well-posed problem.



$\left\{ \begin{array}{l} B: \text{two I.C.s.} \\ R: \text{one B.C.s.} \\ \text{point L: one B.C.s.} \end{array} \right.$ - when $t=0$.
- where it's coming from.

In general, you need

Edge conditions specify the characteristic that are coming INTO the domain of interest (from outside)

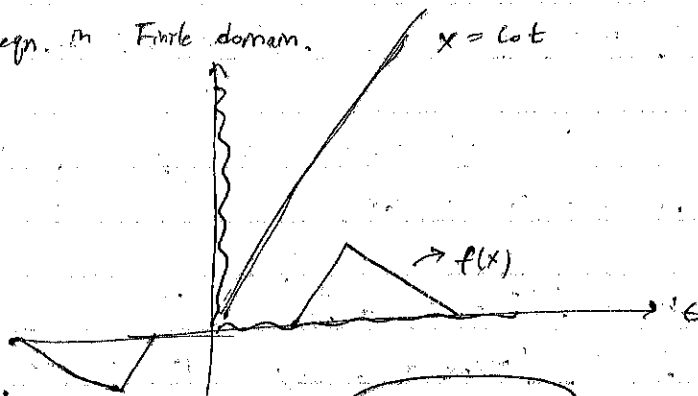


comes in only at edge A, not B.

supersonic system where info. travels at speed of sound relative to flow.

Solution to wave eqn. in finite domain.

$$\begin{cases} 0 \leq x < \infty \\ 0 \leq t < \infty \end{cases}$$

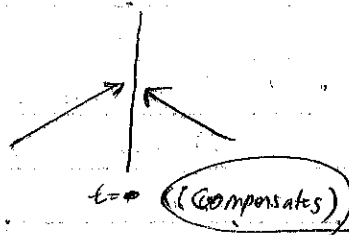


Case 1) $u(x,t) \Big|_{x=0} = 0$

→ Dirichlet B.C.

"Method of images" \equiv Embed into a problem $-\infty < x < \infty$

$$\tilde{f}(x, t=0) = \begin{cases} f(x) & 0 \leq x < \infty \\ -f(-x) & -\infty < x \leq 0 \end{cases}$$



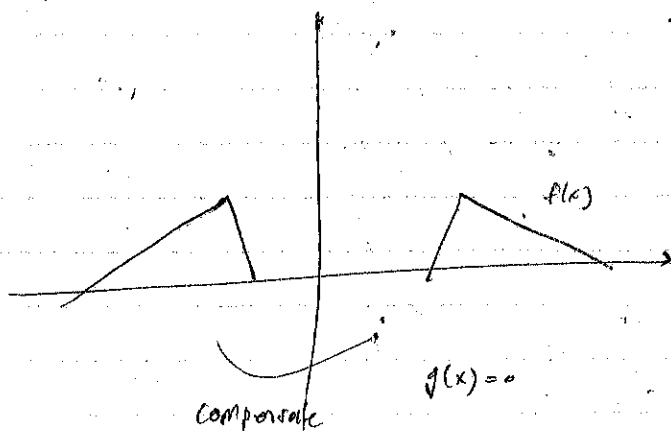
$$u(x,t) = \frac{1}{2} \{ \tilde{f}(x-ct) + \tilde{f}(x+ct) \}$$

$$\begin{cases} x > ct \rightarrow u = \frac{1}{2} \{ f(x+ct) - f(x-ct) \} \\ x < ct \rightarrow u = \frac{1}{2} \{ f(x+ct) + f(x-ct) \} \end{cases}$$

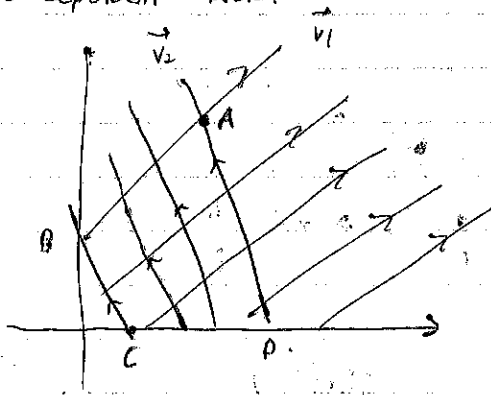
Case 2) $\frac{\partial u}{\partial x} (x=0, t) = 0$

→ Neumann B.C.

$$\tilde{f}(x) = \begin{cases} f(x) & 0 \leq x < \infty \\ f(-x) & -\infty < x < 0 \end{cases}$$



Time dependent B.C.s.

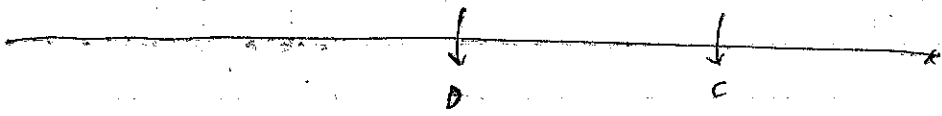


$$u(x=0, t) = h(t)$$

→ $u(A)$ in terms of $u(C)$ and $u(P)$, $h(t_A)$

v_1 is constant along \vec{AB} + v_2 is constant along \vec{BC}

$$u(A) = u(x_A, t_A) = h(t_A - x_A/c) + \frac{1}{2} f(x_A + ct_A) + \frac{1}{2} g(ct_A - x_A)$$



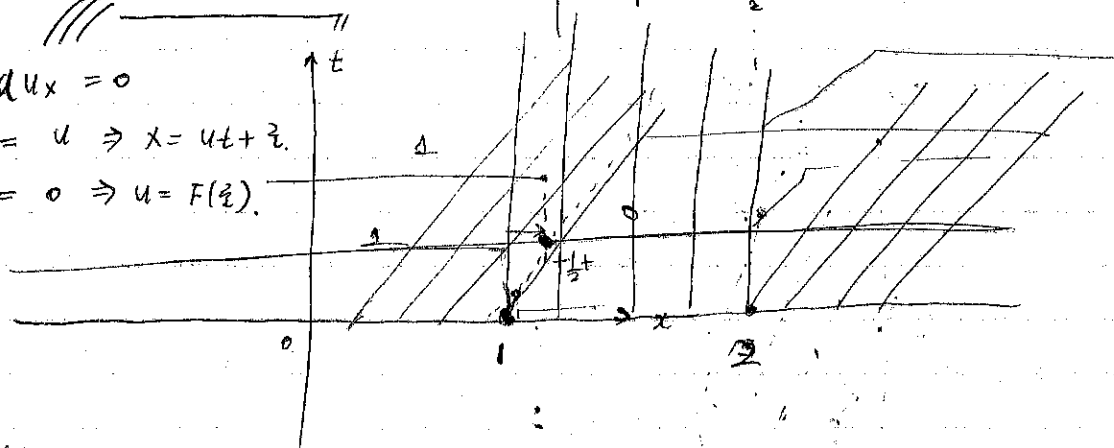
Q)

$$u_t + u u_x = 0$$

$$dx/dt = u \Rightarrow x = ut + \xi$$

$$du/dt = 0 \Rightarrow u = F(\xi)$$

$$u_t + \frac{\partial}{\partial x} \frac{u^2}{2} = 0$$

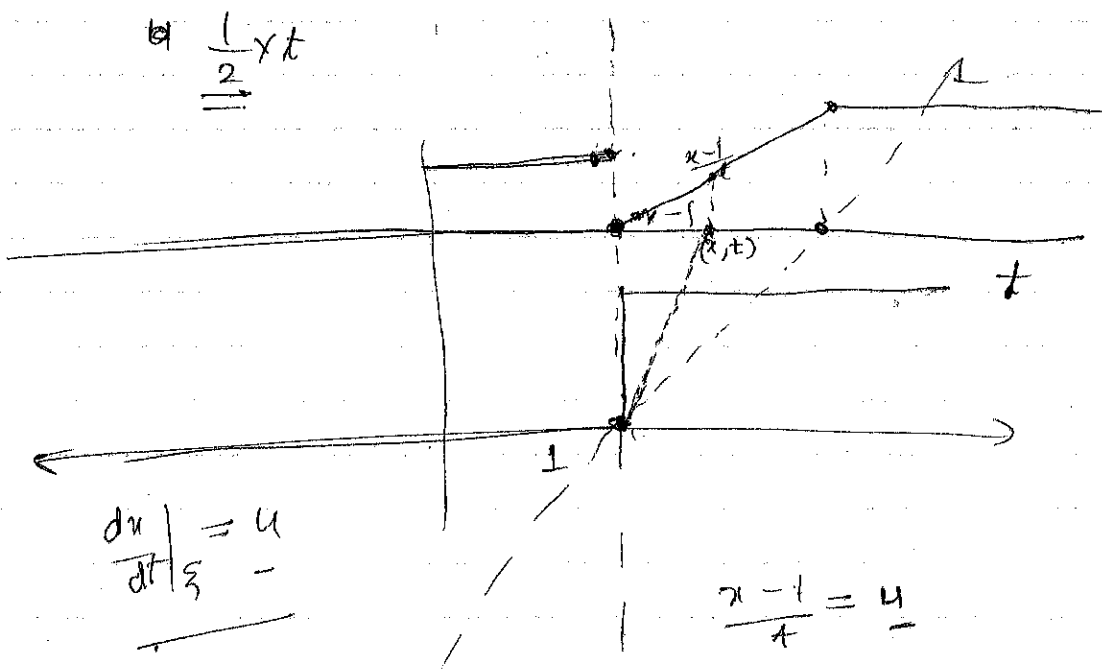


$$\left. \begin{aligned} \xi < 1 & \quad x - t < 1 & \rightarrow u = 1 \\ 1 < \xi < 2 & \quad 1 < x < 2 & \rightarrow u = 0 \\ \xi > 2 & \quad x - t > 2 & \end{aligned} \right\}$$

$$u(x) \quad \text{vs } x$$

$$\frac{u_R + u_L}{2}$$

$$\frac{1}{2} x t$$



$$\frac{du}{dt} \Big|_{\xi} = u$$

$$\frac{x-t}{t} = u$$

02/01/2024

Lecture 8. Separation of variables

$$\partial^2 u / \partial t^2 - c_0^2 \partial^2 u / \partial x^2 = 0 \rightarrow dx/dt = \pm c_0 \begin{cases} \xi^+ = x - c_0 t \rightarrow \textcircled{+} \\ \xi^- = x + c_0 t \rightarrow \textcircled{-} \end{cases}$$

$$\rightarrow \underline{B} = \begin{bmatrix} 0 & -1 \\ -c_0^2 & 0 \end{bmatrix} \text{ where } |\underline{B} - \lambda \underline{I}| = 0.$$

In general, $A u_{xx} + B u_{yx} + C u_{yy} = D \Rightarrow dy/dx = \frac{B \pm \sqrt{B^2 - 4AC}}{2A}$

wave equation is identical to $\frac{\partial u}{\partial \xi \partial \eta} = 0 \Rightarrow u_{\xi \eta} = 0$

Ex) Heat equation: $\partial u / \partial t = \partial^2 u / \partial x^2$ ($0 < x < 1, t > 0$)

B.C.: $u(0, t) = u(1, t) = 0 \quad t > 0$

I.C.: $u(x, 0) = f(x) \quad f(x) \in C^2(0, 1)$ (Class of functions differentiable twice).

Ansatz: $u(x, t) = \phi(t) \psi(x)$

if $u(x, t) \neq 0 \Rightarrow \phi, \psi$ are all non-zeros $\Rightarrow \frac{\phi'}{\phi}(t) = \frac{\psi''}{\psi}(x) = \text{constant}$

$$\Rightarrow \frac{\phi'}{\phi}(t) = \frac{\psi''}{\psi}(x) = -\lambda \quad (\text{because it should not diverge as } t \rightarrow \infty)$$

($\Rightarrow \lambda > 0$)

$$\Rightarrow \phi = A \exp(-\lambda t) \quad \psi = B \cos \sqrt{\lambda} x + C \sin \sqrt{\lambda} x$$

B.C. $\left\{ \begin{array}{l} \psi(0) = \psi(1) = 0 \Rightarrow B = 0, \sqrt{\lambda} = k\pi \Rightarrow \lambda = \pi^2 k^2 \Rightarrow \psi(x) = C \sin(\pi k x) \\ \phi(t) = A \exp(-\pi^2 k^2 t) \end{array} \right.$

$$\Rightarrow u(x, 0) = C \sin(\pi k x) \cdot A = f(x) \Rightarrow AC = \frac{f(x)}{\sin(\pi k x)} \text{ for } 0 < x < 1.$$

$$\Rightarrow u(x, t) = \underbrace{\left(\frac{f(x)}{\sin(\pi k x)} \right)}_{\text{constant}} \exp(-\pi^2 k^2 t) \sin(\pi k x) \quad (X) \text{ useful!}$$

we get. $\psi(x) = C_k \sin(k\pi x) \quad \phi(t) = A \exp(-k^2 \pi^2 t)$

$$\Rightarrow u_k(x, t) = C_k \sin(k\pi x) \exp(-k^2 \pi^2 t)$$

$$\sum_{k=0}^{\infty} u_k(x, 0) = f(x) \Rightarrow \sum_{k=0}^{\infty} C_k \sin(k\pi x) = f(x)$$

Q) How to guarantee $u(x,t) = \sum_{k=1}^{\infty} C_k \cdot u_k(x,t)$ is finite?

$\Rightarrow C_k$ must rapidly go to zero.

[easy way]

$$u(x,t) \Big|_{t=0} = \sum_{k=1}^{\infty} C_k \cdot \sin(k\pi x) \exp(-k^2\pi^2 t) \Big|_{t=0} = \sum_{k=1}^{\infty} C_k \sin(k\pi x) = f(x)$$

$$\Rightarrow \int_0^1 \sum_{k=1}^{\infty} C_k \frac{\sin(k\pi x) \sin(p\pi x)}{\sin(p\pi x)} dx = \int_0^1 f(x) \sin(p\pi x) dx$$

$$\parallel \left\{ \begin{array}{l} C_k \int_0^1 \sin^2 p\pi x dx \quad (k=p) \\ 0 \quad (k \neq p) \end{array} \right. \parallel \int_0^1 f(x) \sin p\pi x dx$$

$$\parallel C_k \int_0^1 \frac{1}{2} (1 - \cos 2p\pi x) dx = \left(\frac{C_k}{2} \right)$$

$$\therefore C_k = 2 \int_0^1 f(x) \sin(k\pi x) dx \quad \rightarrow \quad u(x,t) = \sum_{k=1}^{\infty} C_k u_k(x,t) \quad \#$$

TA Session :

01/02/2024.

Q) Why it not work for point B.C.s. ? \rightarrow Code wrong ?

$$u(x,t) = \frac{1}{2} f(x-ct) + \frac{1}{2} g(x+ct)$$

$$u_2 = \dots + \dots + \dots + \dots$$

if $\alpha_2 = 0$, we only have "right going waves" in the solution.

Method of images.

wave equation on semi-infinite domain.

$$u_{tt} - c^2 u_{xx} = 0, \quad (x \in \mathbb{R} \quad -\infty \leq x < +\infty, \quad t \geq 0)$$

B.C.s : $\frac{\partial u}{\partial x}(0, t) = 0$

I.C.s : $u(x, 0) = \begin{cases} 0 & 0 \leq x < 1 \\ 1 & 1 \leq x < 2 \\ 0 & 2 \leq x < \infty \end{cases}$

* Method of images tries to satisfy the boundary condition.

$\frac{\partial u}{\partial t}(x, 0) = 0$

we presume $\tilde{u}(x, t)$ where

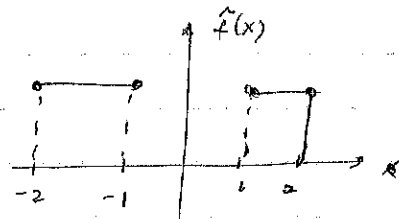
$$\frac{\partial^2 \tilde{u}}{\partial t^2} - c^2 \frac{\partial^2 \tilde{u}}{\partial x^2} = 0, \quad (-\infty \leq x < \infty, \quad t \geq 0)$$

I.C.s : $\tilde{u}(x, 0) = \tilde{f}(x) \rightarrow$ we design this!

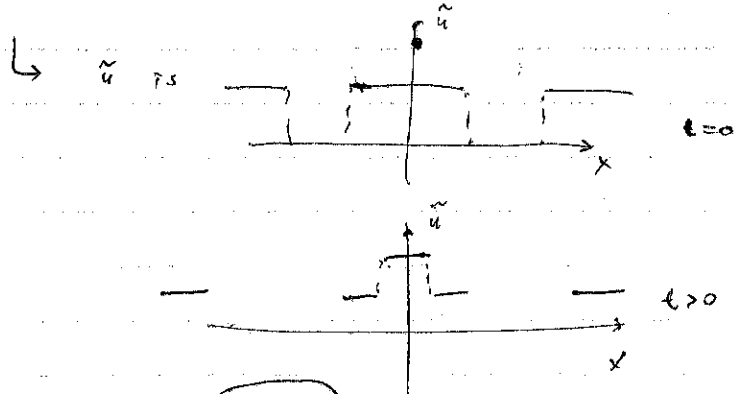
$\frac{\partial \tilde{u}}{\partial t}(x, 0) = 0$

$$\tilde{f}(x) = \begin{cases} f(x) & (x > 0) \\ f(-x) & (x < 0) \end{cases}$$

(even extension of f)



$$\tilde{u}(x, t) = \frac{1}{2} \tilde{f}(x-ct) + \frac{1}{2} \tilde{f}(x+ct) \quad (\text{by d'Alembert's method})$$



$\rightarrow \tilde{u}$ has $\frac{\partial}{\partial x} \tilde{u}(0, t) = 0 \rightarrow$ satisfied!

02/06/2024

Lecture 9. ∞ times differentiable.

Weak derivatives.

Let $C_c^\infty(U)$ a space, compact, ∞ times differentiable and on domain U
 \hookrightarrow compact

\rightarrow Define $\phi: U \rightarrow \mathbb{R}$. Now, consider function $u \in C^1(U)$

$$\int_U u \frac{\partial \phi}{\partial x_i} dx = - \int_U \frac{\partial u}{\partial x_i} \phi dx + \int_{\partial U} u \phi \nu_i dx$$

(': compact space $\rightarrow \partial U \neq \emptyset$)
 " $u \phi$
 for $i=1, 2, \dots, n$ dimensions

Q) what if $u \notin C^1(U) \rightarrow$ still make sense

\Rightarrow find V function that is locally summable. $V = \partial u / \partial x_i$

such that $\int_U u \partial \phi / \partial x_i = - \int_U V \phi dx$

\Rightarrow Integral allows you to not care about u function's differentiability.

Generalization \rightarrow localized.

Suppose $u, v \in L^1_{loc}(U)$ and α is multi-index

$$\int |f(x)| dx < \infty \equiv f \in L^1_{loc}$$

We say v is the α^{th} weak derivative of u s/t

$$v = D^\alpha u \Rightarrow D^\alpha u = \frac{\partial^{\alpha_1}}{\partial x_1^{\alpha_1}} \frac{\partial^{\alpha_2}}{\partial x_2^{\alpha_2}} \dots \frac{\partial^{\alpha_n}}{\partial x_n^{\alpha_n}} u \text{ provided,}$$

$$\int_U u D^\alpha \phi dx = (-1)^{|\alpha|} \int_U v \phi dx \quad \forall \phi \in C_c^\infty(U)$$

E.g.) $u(x) = \begin{cases} x & 0 < x < 1 \\ 1 & 1 < x < 2 \end{cases} \quad v(x) = \begin{cases} 1 & 0 < x < 1 \\ 0 & 1 < x < 2 \end{cases}$

$\Rightarrow u' = v$ except for $x=1 \rightarrow$ Doesn't make sense.

However,

$$\begin{aligned} \int_0^2 u \phi' dx &= + \int_0^1 x \phi' dx + \int_1^2 \phi' dx \\ &= - \int_0^1 \phi dx + \phi(1) - \phi(0) + \phi(2) - \phi(1) \\ &\quad \text{('s bc)} \\ &= - \int_0^1 \phi dx + \phi(2) - \phi(0) = - \int_0^2 v \phi dx \end{aligned}$$

Q) Does it converge?

$$\phi(1+) - \phi(1-) = ?$$

Sobolev space.

Def) $W^{k,p}(U)$ → Sobolev spaces.

$u: U \rightarrow \mathbb{R}$ s.t. for each α , $|\alpha| \leq k$

1) $D^\alpha(u)$ exists (k time differentiable) in the weak sense.

2) and belongs to $L^p(U) \equiv \left(\int_U |f(x)|^p dx \right)^{1/p} < \infty$

A special case ($p=2$).

$$W^{k,2}(U) = H^k(U) \quad \text{s.t.} \quad \left\{ \int_U |f(x)|^2 dx \right\}^{1/2} \equiv \|f\|_2 < \infty$$

$H^0(U) = L^2(U)$ s.t. L^2 norm comes here (L^2 norm is for finite matrix.)

Def) If $u \in H^k(U)$

$$\|u\|_{|k|} = \left[\sum_{|\alpha| \leq k} \left(\int_U |D^\alpha u|^p dx \right)^{1/p} \right]$$

$$\text{Example: } \|u\|_{H^2} = \left(\int_U |u|^2 dx \right)^{1/2} + \left(\int_U \left| \frac{\partial u}{\partial x} \right|^2 dx \right)^{1/2} + \left(\int_U \left| \frac{\partial^2 u}{\partial x^2} \right|^2 dx \right)^{1/2} < \infty$$

Properties of Hilbert spaces.

For every $f, g \in H$ we can define a scalar (f, g)

(f, g) scalar, has

- (1) $(f, g) \geq 0 \quad \forall f, g \in H$
- (2) $(f, f) = 0$ iff $f = 0$
- (3) $(\lambda f, g) = \lambda (f, g)$
- (4) $(f, g) = (g, f)$
- (5) $(f+g, h) = (f, h) + (g, h)$

Eg. 1) $L^2(\Omega)$ with $\Omega \in \mathbb{R}^N$

$$(f, g) = \int_{\Omega} f(x) \overline{g(x)} dx = \langle f | g \rangle$$

Eg. 2) $L^2(\Delta)$ with $\Omega \in \mathbb{R}^N$

$$(f, g) = \int_{\Omega} f(x) g(x) w(x) dx \quad \underline{w(x) > 0}$$

Thm

For H being Hilbert space, if we set $\|f\| = \sqrt{(f, f)}$ then $\|f\|$ is a norm

Orthogonality

$\langle f, g \rangle = 0 \iff f, g$ are orthogonal. (iff) $f, g \in H$

a) can we define orthogonality for $\|f\| = 0$?

Ex.) $f_n(x) = \sin(nx)$ $\{f_n\}_{n=1}^{\infty}$ is orthogonal in L^2

• Infinite orthogonal sequences.

• Equipped with project operator P_E

• $H \setminus \{f_n\}_{n=1}^{\infty}$ is a countable orthogonal set in H if $f_n \neq 0$ for the

simply $n \rightarrow \infty$, $H = \text{span}(\{f_n\}_{n=1}^{\infty})$

then, $P_E g = \sum_{n=1}^{\infty} \frac{(g, f_n)}{(f_n, f_n)} f_n$ (projection)

↳ (if this series converges)

\Rightarrow let $e_n = \frac{f_n}{\|f_n\|}$, $c_n = (g, e_n)$, $E_N = \text{span}\{f_1 \sim f_N\}$

such that $\{e_n\}_{n=1}^{\infty}$ is an orthonormal set.

$$\Rightarrow P_E g = \sum_{n=1}^N c_n e_n$$

note Bessel's inequality

$$\sum_{n=1}^{\infty} |c_n|^2 = \sum_{n=1}^{\infty} |(g, e_n)|^2 \leq \|g\|^2 \quad \therefore \lim_{n \rightarrow \infty} c_n = 0$$



$$\|g\| < \infty$$

• Infinite orthogonal sequences.

Riesz - Fischer Thm

$$\sum_{n=1}^{\infty} c_n e_n \Rightarrow \text{is convergent to } P_E f \equiv g$$

02/08/2024

Lecture 10 - Separation of Variables - operators.

summarize all the materials in lecture 9,

Thm.

Let $\{e_n\}_{n=1}^{\infty} = f_n / \|f_n\|$ be an orthonormal set in (H) .

a) $\{e_n\}_{n=1}^{\infty}$ form a basis in H .

b) $g = \sum_{n=1}^{\infty} (g, e_n) e_n$ for $\forall g \in H$.

* We can define arbitrary inner products (\cdot, \cdot)

= Generalized Fourier series.

c) $\|g\|^2 = \sum_{n=1}^{\infty} |(g, e_n)|^2 \rightarrow$ Bessel's equality.

d) $\{e_n\}_{n=1}^{\infty}$ is complete in H .

• Operators (bounded linear operators).

$$B(X, Y) = \left\{ T: X \rightarrow Y \right. \\ \left. \begin{array}{l} \text{is linear} \\ \|T\|_{X, Y} < \infty \end{array} \right.$$

$$\left(\text{where } \|T\|_{X, Y} = \sup_{f \neq 0} \frac{\|Tf\|_Y}{\|f\|_X} \right) \equiv \text{"maximum is bounded"}$$

Let $\underline{L}u = a_2(x)u'' + a_1(x)u' + a_0(x)u$ on $[a, b]$ domain.

"a general 2nd order diff. operator (o.p.)." $\left(\begin{array}{l} a_j(x) \in C([a, b]) \\ \text{and } a_2(x) \neq 0 \end{array} \right)$

$$\begin{array}{l} \text{P.C.: } B_1 u = c_1 u(a) + c_2 u'(a) \\ B_2 u = c_3 u(b) + c_4 u'(b) \end{array} \left(\begin{array}{l} |c_1| + |c_2| \neq 0 \\ |c_3| + |c_4| \neq 0 \end{array} \right) \Leftrightarrow \left(\begin{array}{l} c_1 \neq 0 \text{ or } c_2 \neq 0 \\ c_3 \neq 0 \text{ or } c_4 \neq 0 \end{array} \right)$$

one can then write a general problem of the form

$$Lu = f(x)$$

$$B_1 u = 0$$

$$B_2 u = 0$$

✓ Adjoint problems.

$$(L\phi, \psi) = \int_a^b (a_2 \phi'' + a_1 \phi' + a_0 \phi) \bar{\psi} \quad \text{- definition of } \int$$

$$= \int_a^b \phi \left((a_2 \psi)'' - (a_1 \psi)' + (a_0 \psi) \right) dx$$

$$= L^* \psi$$

$$= (\phi, L^* \psi)$$

$$\Rightarrow (L\phi, \psi) = (\phi, L^* \psi)$$

$$L^* \psi = a_2 \psi'' + (2a_2' - a_1) \psi' + (a_2'' - a_1' + a_0) \psi$$

$$\text{if } a_1 = a_2' \Rightarrow L^* \psi = L\psi$$

$$\text{Then, it implies } \boxed{(L\phi, \psi) = (\phi, L\psi)} \Rightarrow \text{"self adjoint"}$$

$$\text{Eg.) } \int u'' v dx = \int u v'' dx$$

$$\underbrace{(Lu, v)} = \underbrace{(u, Lv)} \quad (\because a_1 = 0 = a_2' = 1' = 0)$$

✓ On $[a, b]$ define $(L\phi, \psi) - (\phi, L^*\psi) = J(\phi, \psi) \Big|_a^b$
 where $J(\phi, \psi) = a_2 (\phi' \bar{\psi} - \phi \bar{\psi}') + (a_1 - a_2') \phi \bar{\psi}$

$$\text{if } J(\phi, \psi) \Big|_a^b = 0, \text{ then } 'L' \text{ is self-adjoint}$$

$$p(x) < 0.$$

A special case (particular choice).

$$\left. \begin{aligned} p(x) &= \exp\left(\int_a^x \frac{a_1(s)}{a_2(s)} ds\right) & w(x) &= -p(x)/a_2(x) \\ & & q(x) &= a_0(x) \cdot w(x) \end{aligned} \right\}$$

$$p(x) > 0 \Rightarrow w(x) > 0 \in C([a, b]).$$

$$\text{Then, } \boxed{- (p\phi')' + q\phi = \lambda w(x)\phi, \quad (L_0\phi) = \lambda\phi}$$

\hookrightarrow "Sturm-Liouville problem"

Eigenvalue problem.

$$\left. \begin{aligned} \text{def } L_1\phi &= (p\phi')' + q\phi \\ L\phi &= L_1\phi / w(x) \end{aligned} \right\}$$

$$\text{Notice for } \psi, \quad (L_1\phi, \psi) = (\phi, L_1\psi)$$

$$\therefore \int_a^b ((p\phi')' + q\phi)\psi dx \Rightarrow -\int_a^b \psi' p\phi' dx + \int_a^b q\phi\psi dx$$

$$\Rightarrow +\int_a^b (\psi' p)' \phi dx + \int_a^b q\phi\psi dx$$

$$\Rightarrow \int_a^b ((p\psi')' + q\psi)\phi dx = \frac{(\phi, L_1\psi)}{w(x)} \quad \#$$

$$L\phi = L_1\phi / w(x)$$

$$\text{claim: } L_0\phi = \lambda\phi \quad \text{iff} \quad L\phi = \lambda\phi$$

$$\text{Define } (\phi, \psi) = \int_a^b \phi(x) \overline{\psi(x)} w(x) dx$$

$$\|\phi\|_{L_w^2} = \left(\int_a^b |\phi(x)|^2 w(x) dx \right)^{1/2} = \sqrt{(\phi, \phi)}$$

\downarrow
weighted L_2 space

$$3h = \frac{100 \text{ mm}}{4}$$

$$\text{B } 40 \text{ mm / problem}$$

Problem Session

$\frac{\partial^2 \theta^2}{\partial x^2} = \frac{\partial^2 \theta^2}{\partial z^2}$ (symmetric)

$$\frac{\partial T}{\partial t} - \alpha \frac{\partial T}{\partial x} = 0$$

↓

$$\frac{\partial T}{\partial t} - \alpha \Delta T = 0 \xrightarrow{1D} \frac{\partial T}{\partial t} - \alpha \left\{ \frac{1}{R} \frac{\partial}{\partial R} \left(R \frac{\partial T}{\partial R} \right) \right\} + \dots = 0$$

$$\Rightarrow \frac{\partial T}{\partial t} - \alpha \frac{1}{R} \frac{\partial}{\partial R} \left(R \frac{\partial T}{\partial R} \right) = 0$$

① $-\frac{\partial T}{\partial R} = 0$ at $l = R$

② $\frac{\partial T}{\partial R} = h(T - T_m)$ at $b = R$

③ $T = T_m$ at $t = 0$

$$\ln(n'(i))$$

relative loss

Substitute $\tau = \frac{\alpha t}{R^2}$, $\theta = \frac{T - T_m}{R}$, $R^* = R/R$, $N = R/R$, $\tau = t/t_0$

$$\Rightarrow \frac{\partial \theta}{\partial \tau} = \frac{1}{R} \frac{\partial}{\partial R} \left(R \frac{\partial \theta}{\partial R} \right) \quad \theta = \tilde{\theta} + \theta_{ss}$$

$x \rightarrow E_b(x; \theta) \rightarrow \text{Loss} \rightarrow \text{Back-propagate} \rightarrow |\ln(n'(i))|^2$ sort out batch size

↙ x' ← Patch (new) = sorted indices

If it's set $n(i) = 1$ well, sorting algorithm will not sort out ①

02/15/2024.

Lecture 11:

we learned. $\left\{ \begin{array}{l} \text{operator (differentiable)} \\ \text{adjoint} \\ \text{Sturm-Liouville problem.} \end{array} \right.$

$$a_2(x) \phi'' + a_1(x) \phi' + a_0(x) \phi = \phi \mathcal{L}\{\phi\} \quad \forall x \in [a, b]$$

$$p(x) = \exp\left\{ \int a_1(s)/a_2(s) ds \right\} \quad w(x) = -p(x)/a_2(x), \quad q(x) = a_0(x)w(x)$$

Then, $\mathcal{L}\phi = \lambda\phi$ eigen problem is equivalent to,

$$\underline{(-p\phi')' + q\phi = \lambda w\phi}$$

$L\phi$ is self-adjoint.

$$\underline{(p, L\phi) = (\phi, L\psi)}$$

Recall a new weighted space,

$$L_w^2(a, b) = \left\{ \phi \mid \|\phi\|_w^2 = \int_a^b |\phi(x)|^2 w(x) dx < \infty \right\}$$

$$\text{Then, } (\phi, \psi)_w = \int_a^b \phi(x) \bar{\psi}(x) w(x) dx$$

$$\boxed{(L\phi, \psi)_w = (\phi, L\psi)_w} \quad (*)$$

Boundaries,

$$B_1\phi = c_1\phi + c_2\phi'|_a = 0$$

$$B_2\phi = c_3\phi(b) + c_4\phi'(b) = 0$$

$$J(\phi, \psi)|_a^b = p(x) (\phi' \bar{\psi} - \phi \bar{\psi}')|_a^b = 0. \quad \text{If } \psi \text{ has same B.C., } J(\phi, \psi)|_a^b = 0.$$

$\therefore T = \{ B_1, B_2, L \}$ is self-adjoint space

Thm

- a) $L\phi = \lambda\phi$ is equivalent to $L\phi = \lambda\phi$.
- b) $T = \{L, B_1, B_2\}$ is self-adjoint.
- c) T has countable sequence of real, distinct eigenvalues $\{\lambda_n\}_{n=1}^{\infty}$ with $\lambda_n \rightarrow \infty$.
- d) Corresponding eigenfunctions, $\{\phi_n\}$ may be chosen to form a basis of $L^2_w(a, b)$.
- e) These eigenfunctions are orthogonal in the weighted space $L^2_w(a, b)$.

$$\frac{\int_a^b \phi_n \bar{\phi}_m w dx}{\int_a^b \phi_n \bar{\phi}_n w dx} = \begin{cases} 0 & m \neq n \\ 1 & m = n \end{cases}$$

f) Any $f \in L^2_w(a, b)$ can be written as $f = \sum_{n=1}^{\infty} c_n \phi_n$ & $c_n = \underbrace{(f, \phi_n)_w}_{\text{norm}}$.

* Normalization of orthogonal eigenfunctions.

$\{\phi_n\}_{n=1}^{\infty}$ are not orthonormal, they can be normalized using inner product.

e.g.) $\psi_n = \frac{\phi_n}{\sqrt{(\phi_n, \phi_n)_w}}$

* Periodic B.C.s

$$\left. \begin{aligned} \phi(a) &= \phi(b) \\ \phi'(a) &= \phi'(b) \end{aligned} \right\} \Rightarrow \begin{aligned} \phi(a) - \phi(b) &= 0 \\ \phi'(a) - \phi'(b) &= 0 \end{aligned}$$

⇒ Not separable

conditions for a & b are separate

⇒ $\lambda = 0, \phi = 1$

Note: $J(p, \phi)$ is still zero

Homogeneous.

still, (L, p_1, p_2) is still self-adjoint.

→ Additionally, eigenvalues are not simple.

→ For each eigenvalue, there are two eigen functions!

Ex. Consider heat eq. $u_t = u_{xx}$ B.C. $u(0, t) = u(1, t) = 0 \quad \forall t > 0$
 $u(x, 0) = f(x) \quad 0 < x < 1$

$$u_t = c_k e^{-k^2 \pi^2 t} \sin(k \pi x)$$

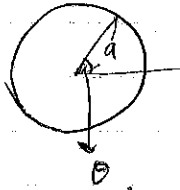
$$u = \sum_{k=1}^{\infty} A_k \exp(-k^2 \pi^2 t) \sin(k \pi x) \quad (\text{general Fourier series})$$

$x_A =$

1+2

Eg. Heated cylindrical rod.

$$x = a \cos \theta, \quad y = a \sin \theta.$$



$$\partial T / \partial t = \nabla^2 T.$$

Using chain-rule,

$$\partial T / \partial t = \frac{1}{r} \frac{\partial}{\partial t} \left(r \frac{\partial T}{\partial r} \right) \quad (\theta - \text{symmetric})$$

$$T(r, 0) = f(r)$$

$T(0, t)$ is finite \rightarrow No blow up.

$$T(a, t) = 0$$

$$\text{sol} \Rightarrow T(r, t) = R(r) \tilde{T}(t)$$

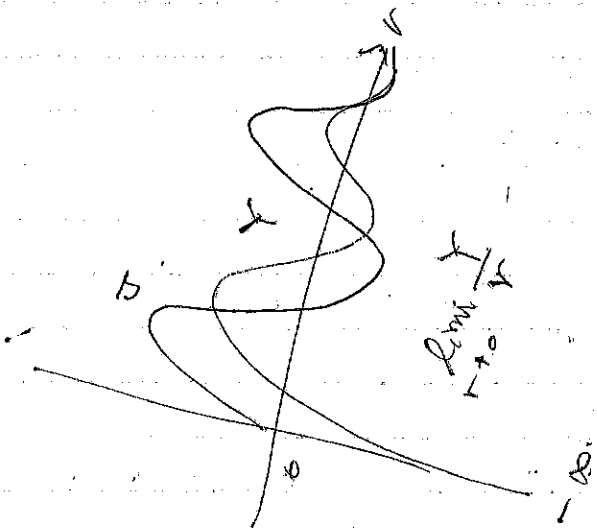
$$\Rightarrow \frac{1}{R} \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial R}{\partial r} \right) = \frac{\tilde{T}'}{\tilde{T}} = \alpha$$

$$\alpha = -\lambda^2 \rightarrow R(a) = 0$$

$$\Rightarrow r^2 R'' + r R' + r^2 \lambda^2 R = 0$$

where Bessel's equation of order ν is, $x^2 \phi'' + x \phi' + (x^2 - \nu^2) \phi = 0$.

$$\text{where } \phi = c_1 \underbrace{J_\nu(x)}_{\text{1st kind}} + c_2 \underbrace{Y_\nu(x)}_{\text{2nd kind}}$$



$$10^{-6} \sim 10^{-8} \quad (100)$$

TA session

02/16/2024

• Sturm-Liouville problem.

$$\mathcal{L}y = -(p(x)y')' + q(x)y - \lambda r(x)y$$

$$\mathcal{L}y / r(x) = \lambda y \quad \rightarrow \quad \boxed{\mathcal{L}_1 y = \lambda y}$$

B.C. (1) $B_1 u = c_1 y(a) + c_2 y'(a) = 0$

(2) $B_2 u = c_3 y(b) + c_4 y'(b) = 0$

• All eigenvalues are real, distinct and can be ordered.

$$\lambda_1 < \lambda_2 < \dots < \infty$$

• Eigenfunctions of distinct eigenvalues are ~~disjoint~~ orthogonal to each other.

$$\langle \phi_m, \phi_n \rangle = \int_a^b r(x) \phi_m \phi_n dx = N_m \delta_{m,n} \quad (J_1(\phi_m) = \lambda_m \phi_m) \quad N_m = \langle \phi_m, \phi_m \rangle$$

• Any function in L^2 and satisfy B.C.

$$f(x) = \sum_{m=1}^{\infty} c_m \phi_m(x) \quad \text{where} \quad \left(c_m = \frac{\langle f, \phi_m \rangle}{\langle \phi_m, \phi_m \rangle} \right)$$

Bessel's equation.

$$t^2 y'' + t y' + (t^2 - \nu^2) y = 0$$

$$y = c_1 J_\nu\left(\frac{t}{\lambda}\right) + c_2 Y_\nu\left(\frac{t}{\lambda}\right)$$

Bessel func.
1st kind
order ν

Bessel func.
2nd kind
order ν

$J_\nu(\lambda x)$
 $Y_\nu(\lambda x)$

$$\lambda x \frac{d}{dx} - \nu^2$$

Modified Bessel equation

$$t^2 y'' + t y' - (t^2 + \nu^2) y = 0$$

$$y = c_1 I_\nu(t) + c_2 K_\nu(t)$$

$$= + i^{-\nu} J_\nu(ix)$$

Not oscillatory in nature

$$\frac{\pi}{2} \left\{ \frac{J_{-\nu}(x) - J_\nu(x)}{\sin \pi \nu} \right\}$$

Singular at $t=0$

Note: $-(p(x)y')' + q(x)y = \lambda r(x)y$ becomes, to express this,

$$x^2 y'' + x y' + (\lambda x^2 - \nu^2) y = 0 \quad (t = \sqrt{\lambda} x)$$

↓

$$\frac{d}{dx} (x y') + \frac{y^2}{x} = \lambda x y$$

$$\Rightarrow \begin{cases} p(x) = x \\ q(x) = \nu^2/x \\ r(x) = x \end{cases}$$

domain $[0, \infty)$

weight function.

For S.L. problem

B.C. ① $y(1) = 0$

② y is well-behaved at 0

$$y(x) = c_1 J_\nu(x) + c_2 Y_\nu(x)$$

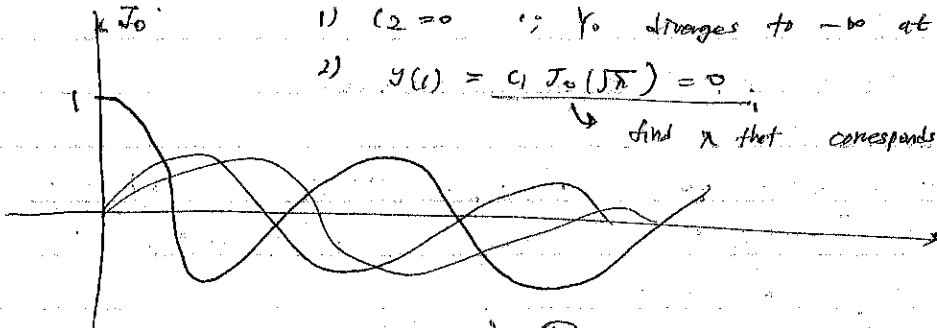
\uparrow \uparrow
 $\sqrt{\lambda}x$ $\sqrt{\lambda}x$

For $\nu = 0$, $y(x) = c_1 J_0(\sqrt{\lambda}x) + c_2 Y_0(\sqrt{\lambda}x)$

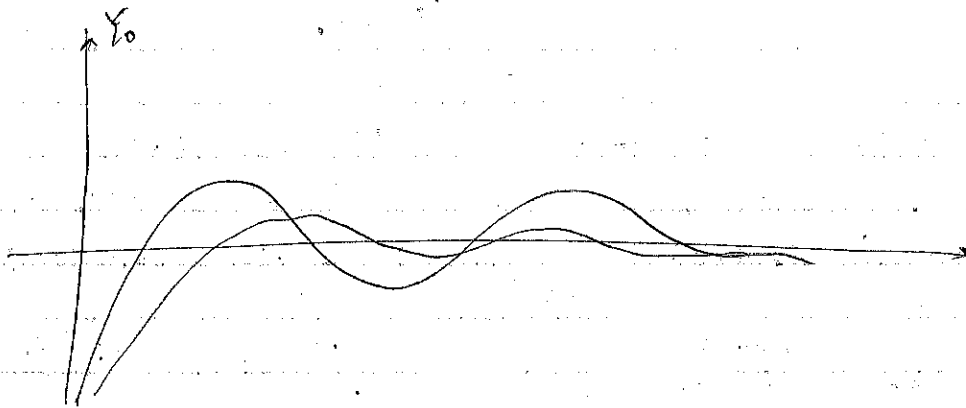
1) $c_2 = 0$; Y_0 diverges to $-\infty$ at $x=0$.

2) $y(1) = c_1 J_0(\sqrt{\lambda}) = 0$

find λ that corresponds to node where $J_0 = 0$



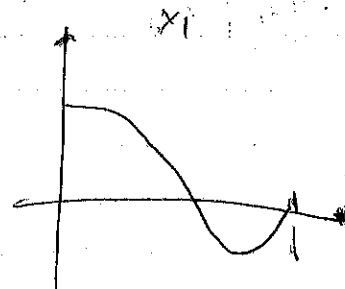
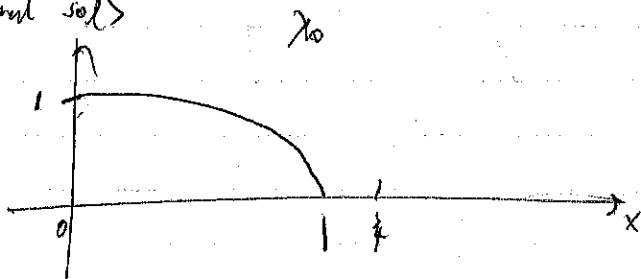
$\lambda = 1.64$



$$\int_0^1 J_0(\lambda_i x) J_0(\lambda_j x) dx = 0 \quad m \neq n$$

weight function!

< Final sol >



Lecture

02/20/2024

ODEs of S.L. problem.

$$r^2 R'' + r R' + \lambda^2 r^2 R = 0$$

$$\Rightarrow -(rR')' = \lambda^2 rR$$

$$\phi(r) = r$$

$$\boxed{w(r) = r}$$

$$\rightarrow (f, g)_w = (f, g)_r \quad (\text{needed for orthogonalization})$$

comparing to.
$$-(p\phi')' + q\phi = \lambda w\phi$$

Bessel

- p

$$x^2 \phi'' + x \phi' + (x^2 - \nu^2) \phi = 0 \rightarrow \phi(x) = c_1 J_\nu(x) + c_2 Y_\nu(x)$$

~~$$\lambda^2 r^2 \phi'' + \lambda r \phi' - \lambda^2 r^2 \phi = 0$$~~

$$\hookrightarrow \phi = c_1 J_0(\lambda r) + c_2 Y_0(\lambda r)$$

↓

Note: we can only handle one non-homogeneity.

(B.C.) $R(1) = 0 \rightarrow J_0(\lambda) = 0 \Rightarrow \lambda = z_n \rightarrow z_n$ zeros of Bessel.

E.g. functions are $J_0(z_n r) \Big|_{n=1}^{\infty}$

$$N_n = \int_{\Omega} J_0(z_n r) J_0(z_m r) \underbrace{r}_{\text{weight function}} dr = N_n \delta_{n,m}$$

$$T(r, t) = \sum_{n=1}^{\infty} c_n J_0(z_n r) e^{-z_n^2 t}$$

$$T(r, t=0) = \sum_{n=1}^{\infty} c_n J_0(z_n r) = f(x)$$

$$\Rightarrow c_n = \frac{(f(r), J_0(z_n r))_w}{(J_0(z_n r), J_0(z_n r))_w}$$

Schrödinger's equation.

02/22/2024

$$\psi(r, \theta, \phi) = R(r) \Theta(\theta, \phi)$$

↓
S.O.V
↓

$$\mathcal{L}\{R(r)\} = \mathcal{L}\{\Theta(\theta, \phi)\} = \text{constant} \rightarrow \text{solve for } R(r)!$$

↓
S.O.V. to $\Theta(\theta, \phi) = \Theta(\theta) \Phi(\phi)$

↓
solve for $\Theta(\theta)$ and $\Phi(\phi)$

Algorithm

Tip 1 Using $\Phi(\phi) = \Phi(\phi + 2\pi)$

$$\exp(i m \phi) = \exp(i m (\phi + 2\pi)) \Rightarrow m \text{ must be integers.}$$

Tip 2 \rightarrow you'll obtain.

$$\sin\theta \frac{d}{d\theta} \left(\sin\theta \frac{d\Theta}{d\theta} \right) + \{ \ell(\ell+1) \sin^2\theta - m^2 \} \Theta = 0$$

Associated Legendre equation

$\rightarrow P_\ell^m(x)$ and $Q_\ell^m(x)$ will be used.

$$Y_\ell^m(\theta, \phi) = N_{\ell m}^{-1} e^{i m \phi} P_\ell^m(\cos\theta)$$

$$N_{\ell m} = \sqrt{\frac{2\ell+1}{4\pi} \frac{(\ell-m)!}{(\ell+m)!}}$$

$$(-1)^m \quad m \geq 0$$

$$i \quad \ell < m < 0$$

Let $u = r R(r) \rightarrow R = u/r$, so the original eq. can be expressed into,

$$\Rightarrow \left(-\frac{\hbar^2}{2m} \frac{d^2 u}{dr^2} + V(r) + \frac{\hbar^2}{2m} \frac{\ell(\ell+1)}{r^2} \right) u = E u$$

mass mass

$$\begin{aligned} -1 \leq x \leq 1 \\ 0 < \theta < \pi \end{aligned}$$

TA session.

02/24/2024.

$$\textcircled{1} \quad \partial T / \partial t = \alpha \nabla^2 T = \alpha \left(\frac{1}{R^2} \frac{\partial}{\partial R} \left(R^2 \frac{\partial T}{\partial R} \right) + \frac{1}{R^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial T}{\partial \theta} \right) \right)$$

$$\rightarrow \text{Sub } \Theta = T / \Delta T \quad \xi = r/R, \quad \tau = \alpha t / R^2$$

I.C. $T(t=0) = \Delta T$

B.C. $T(r=R) = 0$

$T(r=0) = \text{finite}$

$\xi \in [0, 1]$

$$\textcircled{2} \quad \Theta = T(\tau) \cdot H(\xi, \theta) \quad \partial \Theta / \partial \tau = \nabla_{(\xi, \theta)}^2 \Theta \quad \text{SOV 1}$$

$$H \tau' = T \nabla_{(\xi, \theta)}^2 H \Rightarrow T'/T = \frac{1}{H} \nabla_{(\xi, \theta)}^2 H = -\lambda^2 \quad (\because T/T \text{ term})$$

not diverge.

$$\Rightarrow \frac{1}{\xi^2} \frac{\partial}{\partial \xi} \left(\xi^2 \frac{\partial H}{\partial \xi} \right) + \frac{1}{\xi^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial H}{\partial \theta} \right) = -\lambda^2 H$$

$$\textcircled{3} \quad H = R(\xi) \Psi(\theta) \quad \text{SOV 2}$$

$$-\frac{1}{R} \left\{ \frac{\partial}{\partial \xi} \left(\xi^2 \frac{\partial R}{\partial \xi} \right) + \lambda^2 R \xi^2 \right\} = \frac{1}{\Psi} \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \Psi}{\partial \theta} \right) = -\beta^2 \quad (\text{why } -\beta^2?)$$

$\leftarrow \theta\text{-space} \rightarrow$ $\textcircled{\beta}$
 \hookrightarrow s.l. problem using Legendre, eq.

* $P_m^l(x)$ are finite at the end points.

$0 < \theta < \pi$, finite (should be).

$$\left\{ \text{space} \right\} \quad \frac{1}{\xi^2} \frac{\partial}{\partial \xi} \left(\xi^2 \frac{\partial R}{\partial \xi} \right) - \frac{\beta^2 R (m+1)}{\xi^2} R = -\lambda^2 R \quad \because R(\xi=1) = 0$$

$$R(\xi=0) \rightarrow \text{finite} < \infty$$

$\Rightarrow \beta$ spherical

$$R = A \int_{\lambda_m}^{\infty} (Y_{\lambda}^m) + B \int_{\lambda_m}^{\infty} (Y_{\lambda_m}^m) \quad (\infty \text{ constant})$$

$$\Rightarrow R(\xi) = \sum_m (\lambda_m \xi)$$

$$\therefore H = R(\xi) \Theta(\theta)$$

$$\Theta(\theta) = \sum_{m=0}^{\infty} \sum_{m=1}^{\infty} A_{mm} \exp(-\lambda_{mm} \tau) \cdot \sum_m (\lambda_m \xi) P_m(\cos \theta)$$

$$\int_{\theta=0}^{\pi} \sin \theta f(z, \theta) P_S(\cos \theta) d\theta = \sum_{m=1}^{\infty} A_{sm} j_S(\lambda_{sm} r) \frac{2}{2S+1}$$

Now, integrate w.r.t to ξ

$$\Rightarrow \int_0^1 z^2 G_S(\lambda_{sm} z) \int_{\theta=0}^{\pi} \sin \theta f(z, \theta) N_S(\sin \theta) d\theta =$$

Example problem HW5 #3.

$$\Delta u = 4, \quad u(x, y) = 1 \quad r=1 \quad y > 0$$
$$u(x, y) = 0 \quad r=1 \quad y < 0.$$

$$u = r^2 + u_H$$

$$\Rightarrow \Delta u_H + 4 = 4 \Rightarrow u_H = 0 \quad \text{where } u_H = 0 \quad y > 0$$
$$u_H = -1 \quad y < 0. \quad \left. \vphantom{\Delta u_H + 4 = 4} \right\} \text{new problem.}$$

$$\left(\begin{array}{ll} R\theta = 0 & r=1 \quad 0 < \theta < \pi \\ R\theta = -1 & r=1 \quad \pi < \theta < 2\pi \end{array} \right) \text{B.C.'s.}$$

$$\Rightarrow \left\{ \begin{array}{ll} \theta(0) = 0 & 0 < \theta < \pi \\ \theta(\theta) = -\frac{1}{R(\theta)} & \pi < \theta < 2\pi \end{array} \right\}$$

constant.

Schrödinger eq. continued.

$$\frac{1}{R} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) + \left(-\frac{2m r^2}{\hbar^2} \right) \left[\underbrace{V(r)}_{\text{radial term}} - E \right] R = \frac{l(l+1)R}{r^2}$$

$$V(r) = \frac{-e^2}{4\pi\epsilon_0} \frac{1}{r}$$

Substitution : $u = r R(r)$, $R = u/r$

$$\frac{dR}{dr} = \frac{\left\{ r \frac{dR}{dr} + (-u) \right\}}{r^2}$$

Remap.

$$\rightarrow + r \frac{d^2 u}{dr^2} + \frac{R m r}{\hbar^2} V(r) + l(l+1) R = \frac{2m r}{\hbar^2} E u$$

multiply by $\frac{\hbar^2}{2m r}$

$$\Rightarrow -\frac{\hbar^2}{2m} \frac{d^2 u}{dr^2} + V(r) + l(l+1) \frac{\hbar^2}{2m r^2} u = E u$$

$$\Rightarrow -\frac{\hbar^2}{2m} \frac{d^2 u}{dr^2} + \left\{ V(r) + \frac{\hbar^2}{2m} \frac{l(l+1)}{r^2} \right\} u = E u$$

let $\rho = kr$ & $\epsilon_0 = \frac{m e^2}{2\pi \epsilon_0 \hbar^2 k}$

$$\Rightarrow \frac{d^2 u}{d\rho^2} = \left\{ 1 - \frac{\epsilon_0}{\rho} + \frac{l(l+1)}{\rho^2} \right\} u$$

As $\rho \rightarrow \infty$,	$\left\{ \begin{array}{l} e^\rho \rightarrow \infty \text{ as } \rho \rightarrow \infty \\ u(\rho) \sim A e^{-\rho} \\ (\text{large } \rho) \end{array} \right\}$	$\rho \rightarrow 0$, $\frac{l(l+1)}{\rho^2}$ dominates.
$\frac{d^2 u}{d\rho^2} = u$		$\frac{d^2 u}{d\rho^2} = \frac{l(l+1)u}{\rho^2}$
$\Rightarrow u = A e^{-\rho} + B e^{\rho}$		

$$\Rightarrow \rho \frac{d^2 u}{d\rho^2} + 2(l+1-\rho) \frac{du}{d\rho} + (\epsilon_0 - 2(l+1)) u = 0$$

$$\nu = 2l+1, \quad \kappa = 2\rho.$$

We obtain, $x\phi'' + (\nu+1-x)\phi' + \lambda\phi = 0$.

↓
Associated Laguerre Eq.

$$\underline{L_{\nu}^{\rho}(x) = (-1)^{\rho} \left(\frac{d}{dx}\right)^{\rho} L_{\nu}(x)}$$

$$L_{\nu}(x) = e^x \left(\frac{d}{dx}\right)^{\nu} (e^{-x} x^{\nu})$$

where $a_{j+1} = \left\{ \frac{2(j+l-1) - \rho_0}{(j+1)(j+2l-2)} \right\} a_j$ $\left(\binom{\nu}{j} \right)_{\max} = 0$ $2(\nu_{\max} + l + 1) - \rho_0 = 0$

Let $n = \nu_{\max} + l + 1$

$2n - \rho_0 = 0 \Rightarrow n$

↓
(principal quantum #)

$$\boxed{E_n = - \left\{ \frac{m}{2\hbar^2} \left(\frac{e^2}{4\pi\epsilon_0} \right)^2 \right\} \frac{1}{n^2} \quad \forall n=1, 2, \dots}$$

↳ Bohr formula

$$\Rightarrow \psi_{n,l,m}(r, \theta, \phi) = R_{nl}(r) \cdot Y_l^m(\theta, \phi)$$

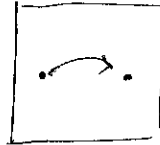
$$R_{nl}(r) = \frac{1}{r} \rho^{l+1} e^{-\rho} v(\rho)$$

$$v(\rho) = \int_{n-l-1}^{2l+1} (2\rho)$$

$$\psi_{n,l,m} = \left(\frac{a}{na}\right)^3 \frac{(n-l-1)!}{2n(n+l)!} e^{-r/na} \left(\frac{2r}{na}\right)^l \int_{n-l-1}^{2l+1} \left(\frac{2r}{na}\right) Y_l^m(\theta, \phi)$$

$$dx_t = -\nabla E X_t + \epsilon_t N(0, \Delta t)$$

$$\Delta x = -\nabla E \Delta t + \epsilon N(0, \Delta t)$$



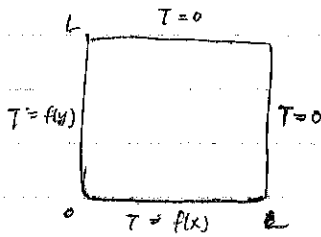
Inhomogeneities.

Linear PDE for S.O.V.

Separable $\left\{ \begin{array}{l} \text{SOV ansatz} \\ \text{gives ODES.} \end{array} \right\} \Rightarrow$ separates $\left| \text{각 다른 일.} \right.$

All but 1 condition have to be homogenous.

Eg. simple inhomogeneity.



$$T(x, y) = T_1 + T_2$$

$$T_1(x, 0) = f(x)$$

$$T_2(x, 0) = 0$$

$$T_1(x, L) = 0$$

$$T_2(x, L) = 0$$

$$T_1(0, y) = 0$$

$$T_2(0, y) = g(y)$$

$$T_1(L, y) = 0$$

$$T_2(L, y) = 0$$

S.O.V & Transformations.

02/29/2024.

Inhomogenities \Rightarrow Idea of Superposition (Linear).

$$T_{xx} + T_{yy} = 0 \quad \begin{matrix} T(x,0) = f(x) & T(x,L) = 0 \\ T(0,y) = g(y) & T(L,y) = 0 \end{matrix}$$

$$\Rightarrow T(x,y) = \sum_{n=1}^{\infty} A_n \cdot \sin\left(\frac{n\pi y}{L}\right) \sinh\left(\frac{n\pi(L-x)}{L}\right) \rightarrow \text{How to calculate } A_n?$$

By linearity, $T(x,y) = T_1(x,y) + T_2(x,y)$.

(T₂) will satisfy $T_2(x,0) = f(x)$ $T_2(x,L) = 0$
 $T_2(0,y) = 0$ $T_2(L,y) = 0$

(T₁) will satisfy $T_1(x,0) = 0$ $T_1(x,L) = 0$
 $T_1(0,y) = g(y)$ $T_1(L,y) = 0$

One inhomogeneity at a time!
 (solve for

2 inhomogeneity \rightarrow divided into 1 homogeneity \rightarrow Add again

General inhomogenities.

$$\frac{\partial}{\partial x} \left(\frac{1}{r} \frac{\partial u}{\partial x} \right) = \frac{\partial u}{\partial t} - f(r,t) \quad f(r,t) = \sum_{n=1}^{\infty} C_n \phi_n \quad \begin{pmatrix} u(r=0,t) < \infty \\ u(r,L=0) = 0. \end{pmatrix}$$

$$T(t) = ae^{-\lambda^2 t}, \quad R(r) = a J_0(z_n r)$$

$$u = \sum R(r) T(t) \quad (\text{sol of } \textcircled{\text{Homo}})$$

$$u = u^h + u^p \rightarrow (\text{sol to inhom. with zero B.C.})$$

\downarrow
 (sol to homo)

$$u^p(r,t) = \sum_{n=1}^{\infty} A_n(t) J_0(z_n r) \rightarrow \text{substitute back into PDE}$$

$$\sum_n A_n(t) (J_0(z_n r))'' = \sum_n \frac{dA_n(t)}{dt} J_0(z_n r)$$

$$\sum_n A_n(t) z_n^2 J_0(z_n r)$$

$$\sum_n \frac{dA_n(t)}{dt} J_0(z_n r) - C_n(t) J_0(z_n r)$$

(\because property of Bessel func)

since orthogonal, $-A_n(t) z_n^2 = -C_n(t) + dA_n(t)/dt$

Therefore, $dA_n(t)/dt = C_n(t) - A_n(t) z_n^2$

$$A_n(t) = \int_0^t e^{z_n(t-t')} C_n(t') dt'$$

$$C_n(t) = \frac{\langle \psi(x, t) | \hat{p}_n \rangle}{\langle \phi_n | \phi_n \rangle}$$

— End of S.O.V —

$$\frac{\psi(x-y, t-t')}{\psi(x, t)}$$

$$x = x - y$$
$$t = t - t'$$

Fourier transform

02/29/2024

$$\mathcal{F}\{f(x)\} = \frac{1}{(2\pi)^{N/2}} \int_{-\infty}^{\infty} f(z) e^{jkz} dz = \hat{f}(k)$$

$$f(x) = \frac{1}{(2\pi)^{N/2}} \int_{-\infty}^{\infty} \hat{f}(k) e^{-jkx} dx$$

$$\mathcal{F}\{f(x)\} = \hat{f}(k) = \frac{\gamma}{2\pi} \int_{-\infty}^{\infty} f(z) e^{ajkz} dz$$

$$f(x) = \frac{1}{\gamma} \int_{-\infty}^{\infty} \hat{f}(k) e^{ajkx} dk$$

choose $\gamma = \sqrt{2\pi}$, $a = +1 \rightarrow$ makes sense (when f, \hat{f} are integrable)

* Properties

1) $\mathcal{F}\{f'\} = -jk \mathcal{F}\{f\}$

$\mathcal{F}\{f''\} = -k^2 \mathcal{F}\{f\}$

2) convolution

$\mathcal{F}\{f\} = \hat{f}(k)$

$\mathcal{F}\{g\} = \hat{g}(k)$

$\mathcal{F}\{f * g\} = \hat{f}(k) \hat{g}(k)$
 ↓
 convolution

$f * g = \frac{1}{2\pi} \int_{-\infty}^{\infty} g(z) f(x-z) dz$

* Fundamental Sol.

$u_t - u_{xx} = \phi(x, t) \quad -\infty < x < \infty$

Formulate as, $u_t - u_{xx} = \delta(x-z) \cdot \delta(t-t')$

↳ solution is $F(x-z, t-t')$

Then, we know solution is

$$u(x, t) = \int_{-\infty}^{\infty} \int_0^t F(x-z, t-t') \cdot \phi(z, t') dt' dz$$

$$\begin{aligned} \frac{u_t - u_{xx}}{u_t + k^2 u} &= \frac{\delta(x-z) \delta(t-t')}{\delta(t-t')} \\ &= \frac{\delta(t-t')}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \frac{\delta(x-z) e^{jkx} dx}{\delta(x-z)} \\ &= e^{jkz} \end{aligned}$$

$$\begin{aligned} \hat{u}(k, t) &= \frac{1}{\sqrt{2\pi}} e^{-k^2 t} \\ \Rightarrow u(x, t) &= \int_{-\infty}^{\infty} \frac{1}{2\pi} e^{-k^2 t} e^{-jkx} dk \end{aligned}$$

Solve for $z=0, t'=0 \Rightarrow \hat{u}_t + k^2 u = \delta(t)/\sqrt{2\pi}$

$$u(x,t) = \int_{-\infty}^{\infty} \frac{1}{2\pi} e^{-k^2 t} e^{-ikx} dk$$

if $m = \frac{x}{2t^{1/2}} \Rightarrow$ then e^{-m^2} is analytic.

$$\Rightarrow G(x,t) = \sqrt{\pi} e^{x^2/2t^{1/2}}$$

- Calculate rates.

1) $states = (-1, 1, 0)$

2) $rate = \begin{bmatrix} 0 & 0 & 0 & 0 \\ p_1 & p_2 & p_3 & p_4 \end{bmatrix}$

3) $k = \begin{bmatrix} 0 & 0 & 0 & 0 \\ p_1 & p_2 & p_3 & p_4 \end{bmatrix}$

4) $prates = (p_1', p_2', p_3', p_4')$

5) if. success

Initial: $states = (-1, 1, 0)$

$rates = (p_1, p_2, p_3, p_4)$

Fourier Transform - example.

- $\widehat{\partial \phi / \partial x} = jk \hat{\phi}$
- $\widehat{\partial^2 u / \partial x^2} = \frac{\partial}{\partial x} \frac{\partial \hat{u}}{\partial x} = jk \widehat{\partial u / \partial x} = jk jk \hat{u} = -k^2 \hat{u}(k, t)$
- $\widehat{\partial^2 u / \partial t^2} = \partial^2 \hat{u} / \partial t^2$

$$\begin{aligned} \partial^2 u / \partial t^2 + (-c^2) \partial^2 u / \partial x^2 &= 0 & \xrightarrow{\text{Fourier Transform}} & \partial^2 \hat{u} / \partial t^2 + c^2 k^2 \hat{u}(k, t) = 0 \\ \left\{ \begin{aligned} u(x, 0) &= f(x) \\ \partial u / \partial t(x, 0) &= 0 \end{aligned} \right. & & \hat{u}(k, t) = \hat{A}(k) \exp(-jkt) \\ & & & \hat{u}(k, 0) = \hat{f}(k) \\ & & & \partial \hat{u}(k, 0) / \partial t = 0 \end{aligned}$$

$$\phi(x, t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \hat{f}(k) \cdot e^{-k^2 t - jkx} dk$$

if $\hat{f}(k) \in$

$$f(x) \times$$

$$\phi(x, t) = f(x) \times \mathcal{F}^{-1}\{e^{-k^2 t}\}$$

$$e^{-x^2} \times f(x) = f(\tau) e^{-(x-\tau)^2}$$

1. $\frac{\partial T}{\partial t} = \alpha \nabla^2 T = \alpha \frac{\partial^2 T}{\partial x^2}$

(a)

	\tilde{T}	x	t	β	α	
degrees	1	0	0	1	0	$m=3, n=5$
length	0	1	0	-1	2	$n-m = 2$ π groups
time	0	0	1	-1	-1	$\tilde{T} = T - T_0$ (B.C. is still)

$\left. \begin{aligned} \tilde{T}(x, t=0) &= 0 \\ \tilde{T}(x \rightarrow \infty, t) &\rightarrow T_0 \\ -T_x(x=0, t) &= \beta t \end{aligned} \right\} \text{ satisfies for } \tilde{T} \quad \underline{\pi_1 = f(\pi_2)}$

(b) $\tilde{T} = T - T_0 = B t^m F(\eta) \quad \eta = x / (A t^n)$

LHS: $\frac{\partial \tilde{T}}{\partial t} = m B t^{m-1} F(\eta) + B t^m F'(\eta) \cdot (x/A) \cdot \{-n t^{-n-1}\}$

RHS: $\alpha \frac{\partial^2 T}{\partial x^2} = \alpha \frac{\partial}{\partial x} \left\{ \beta t^m F'(\eta) \cdot \frac{1}{A t^n} \right\} = \alpha \beta t^m F''(\eta) \left(\frac{1}{A t^n} \right)^2$

\Rightarrow t order should match $\rightarrow m-n-1 = m-2n \Rightarrow \boxed{n = \frac{1}{2}}$

B.C.: $-T_x(x=0, t) = -\beta t^m F'(\eta) \cdot \frac{1}{A t^n} \Big|_{x=0} = \beta t^1$

$\Rightarrow m-n=1 \Rightarrow \boxed{m = \frac{3}{2}}$

PDE becomes, $\frac{3}{2} B t^{1/2} F(\eta) + B t^{3/2} F'(\eta) \frac{x}{A} \left(-\frac{1}{2} t^{-3/2} \right) = \alpha \beta t^m F''(\eta) \left(\frac{1}{A t^n} \right)^2$

$2F'' + \eta F' - 3F = 0, F(0) = 1, F(\infty) = 0.$

$\boxed{A = \sqrt{\alpha}} \quad \boxed{B = -\beta \sqrt{\alpha}}$

(c) Superposition.

2. (a)

	c	x	t
deg.			
time			
length			

$$\omega = 1/2 \quad m = 0$$

$$0 = F''F + (F')^2 + 2kF \quad F(0) = 1, F$$

$$m \begin{cases} \text{Length} \\ \text{time} \\ \text{depth} \end{cases} \left| \begin{array}{c} n \\ \hline \tilde{H} \times t^\alpha \end{array} \right. \quad n-m = 1 < \# \text{ var.}$$

$$3. \quad \partial H / \partial t = - \frac{\gamma}{3\mu} \frac{\partial}{\partial x} \left\{ H^3 \frac{\partial^3 H}{\partial x^3} \right\}$$

$$(a) \quad H(x,t) = B t^{mm} F(\eta) \quad \text{where } \eta = \frac{x}{A t^n}$$

$$\begin{aligned} \text{LHS: } \partial H / \partial t &= m B t^{m-1} F(\eta) + B t^{mm} F'(\eta) \cdot (-n) \frac{x}{A t^{n+1}} \\ &= B t^{m-1} \{ m F - n \eta F' \} \end{aligned}$$

$$\text{RHS: } - \frac{\gamma}{3\mu} \frac{\partial}{\partial x} \left\{ H^3 \frac{\partial^3 H}{\partial x^3} \right\} = - \frac{\gamma}{3\mu} \left\{ 3 H^2 \frac{\partial H}{\partial x} \frac{\partial^3 H}{\partial x^3} + H^3 \frac{\partial^4 H}{\partial x^4} \right\}$$

$$\partial H / \partial x = B t^{mm} F'(\eta) \frac{1}{A t^n} = \frac{B}{A} t^{m-n} F'(\eta)$$

$$\partial^2 H / \partial x^2 = \frac{B}{A^2} t^{m-2n} F''(\eta)$$

$$\partial^3 H / \partial x^3 = \frac{B}{A^3} t^{m-3n} F'''(\eta)$$

$$\partial^4 H / \partial x^4 = \frac{B}{A^4} t^{m-4n} F''''(\eta)$$

$$\text{RHS: } - \frac{\gamma}{3\mu} \left\{ 3 \cdot B^2 t^{2m} (F(\eta))^2 \cdot \frac{B}{A} t^{m-n} F'(\eta) \cdot \frac{B}{A^3} t^{m-3n} F'''(\eta) \right.$$

$$\left. + B^3 t^{3m} F^3 \frac{B}{A^4} t^{m-4n} F''''(\eta) \right\}$$

$$= - \frac{\gamma}{3\mu} \left\{ 3 \frac{B^4}{A^4} \cdot (F(\eta))^2 F'(\eta) F'''(\eta) \cdot t^{4m-4n} \right.$$

$$\left. + \frac{B^4}{A^4} F^3 F''''(\eta) \cdot t^{4m-4n} \right\}$$

$$\therefore m-1 = 4m-4n \Rightarrow \underline{3m = 4n-1} \quad (\because \text{RHS} = \text{LHS})$$

and

$$m = 1/4 \quad n = -1/4 \quad (\because m+n=0)$$

form (12) - integral condition.

$$\begin{cases} c_p/c_v = \gamma \\ \rho U^2 = c_0 \end{cases}$$



4. $K \propto \sqrt{T}$ $c_p \propto \gamma T^2$

$$\frac{\partial T}{\partial x}(x=0, t) = 0$$

$$T(\infty, t) = 0$$

$$\frac{\partial}{\partial x} \left\{ \sqrt{T} \frac{\partial T}{\partial x} \right\} = \gamma T^2 \frac{\partial T}{\partial t}$$

$$T(x, 0) = 0$$

$$\gamma \int_0^{\infty} T^3 dx = \beta$$

	T	x	t	γ	β
{L}	0	1	0	-2	
{T}	0	0	1	1 1	
{K}	1	0	0	-3/2	

$$n - m = 5 - 3 = 2$$

$$\rightarrow \pi_1, \pi_2 = f^A(\pi_1)$$

exists!
 Simm. Sol.

$$\text{det } \pi_1 = \begin{pmatrix} a & b & c & d \\ x & t & \gamma & \beta \end{pmatrix} = 0$$

$$\pi_2 = \begin{pmatrix} a & b & c & d \\ x & t & \gamma & \beta \end{pmatrix} = 0 \rightarrow$$

set same (defn of π)

$$a - 2c - d = 0 \rightarrow a = 1$$

$$b + c + d = 0 \rightarrow b = -3/3$$

$$3/2(d - c) = 0 \rightarrow c = d = 1/3$$

$$1 - \frac{3}{2}c + \frac{3}{2}d = 0$$

$$-2c - d = 0$$

$$d = -2c$$

$$2c = -d$$

$$1 - \frac{3}{2}c + \frac{3}{2}(-2c) = 0$$

$$1 - \frac{3}{2}c - 3c = 0$$

$$c = \frac{2}{9} \quad d = -\frac{4}{9}$$

$$\nabla V \cdot \nabla q - \beta^{-1} \nabla^2 q = 0.$$

$$f = \exp\left(\frac{-\beta}{2} \cdot E_b\right)$$

~~$$\nabla q = -\nabla E_b \exp\left(-\frac{\beta E_b}{2}\right).$$~~

$$\nabla q = -\frac{\beta}{2} \cdot \nabla E_b \exp\left(-\frac{\beta}{2} E_b\right) = \left(-\frac{\beta}{2} \nabla E_b\right) \boxed{\exp}$$

$$\nabla^2 q = -\frac{\beta}{2} \nabla^2 E_b \exp\left(-\frac{\beta}{2} E_b\right) + \left(\frac{\beta}{2} \nabla E_b\right)^2 \exp\left(-\frac{\beta}{2} E_b\right) = 0$$

$$= \left[-\frac{\beta}{2} \nabla^2 E_b + \left(\frac{\beta}{2} \nabla E_b\right)^2\right] \boxed{\exp}$$

$$\nabla V \left(-\frac{\beta}{2} \nabla E_b\right) \cancel{\exp} - \beta^{-1} \left[-\frac{\beta}{2} \nabla^2 E_b + \left(\frac{\beta}{2} \nabla E_b\right)^2\right] \cancel{\exp} = 0.$$

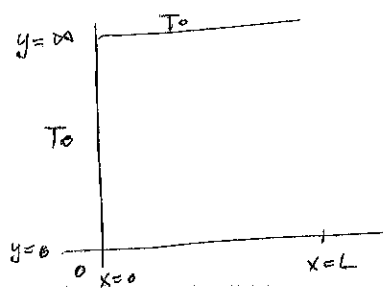
$$\Rightarrow -\frac{\beta}{2} \nabla V \nabla E_b - \beta^{-1} \left[-\frac{\beta}{2} \nabla^2 E_b + \frac{\beta^2}{4} (\nabla E_b)^2\right] = 0$$

$$\Rightarrow -\frac{\beta}{2} \nabla V \nabla E_b - \frac{\beta^2}{4} (\nabla E_b)^2 + \frac{1}{2} \nabla^2 E_b = 0$$

$$\Rightarrow \nabla^2 E_b = \beta \nabla V \nabla E_b + \frac{\beta^2}{2} (\nabla E_b)^2$$

$$\text{p.c. 1: } \exp\left(-\frac{\beta}{2} E_b\right) = 0 \quad (x \in \partial A)$$

$$\exp\left(-\frac{\beta}{2} E_b\right) = 1 \quad (x \in \partial B)$$



5. $\beta h^2 \frac{\partial T}{\partial x} = \alpha \frac{\partial^2 T}{\partial y^2}$

a) Using algebraic similarity,

b) $\tilde{T} = T - T_0$ * $\tilde{x} = x/L$, $h = \beta y$.

$$\frac{\partial T}{\partial x} = \frac{\partial \tilde{T}}{\partial T} \left(\frac{\partial T}{\partial \tilde{T}} \right) \cdot \frac{\partial \tilde{T}}{\partial x} \cdot \frac{\partial x}{\partial \tilde{x}} \left(\frac{\partial \tilde{x}}{\partial x} \right)$$

$$= \frac{\partial \tilde{T}}{\partial \tilde{x}} \cdot 1 \cdot \frac{1}{L}$$

$$\tilde{T} = T - T_0 = B x^m F\left(\frac{y}{Ax^n}\right)$$

$$m = 1/(2+\gamma) \quad , \quad n = 1/(2+\gamma)$$

$$A = k, B = -q \text{ (you choose),}$$

$$F'(0) = 1, F(\infty) = 0$$

$$\frac{\alpha}{k^2} F'' - \beta h^2 k^{\gamma} \left(\frac{F}{2+\gamma} - \frac{h F'}{2+\gamma} \right) = 0.$$

$$\Rightarrow (2+\gamma) F'' = h^{\gamma} (F - \gamma F')$$

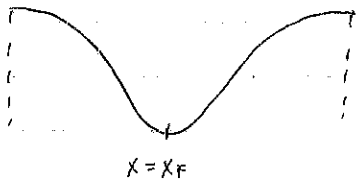
$$T - T_0 = B x^m F\left(\frac{y}{Ax^n}\right)$$

6. $m = -1$ $C = B L^m F\left(\frac{y}{Ax^n}\right)$

$$n = 1/2$$

$$\int A e^{-k^2} = 1$$

$$k(i \rightarrow 0) = 0$$



$$f(0) = 0 = k(0 \rightarrow 1)$$

$f(0) = k(0 \rightarrow 1) \cdot f(1) + k(0 \rightarrow 4) \cdot f(4)$ (contradiction).
 $f(0) = 1$

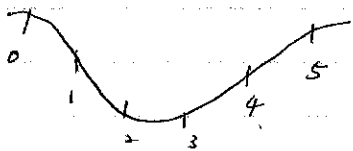
8979323 8.46

$$e^{-x^2}$$

$$1/\sqrt{2} = 0$$

$$2\sigma^2 = 1$$

0.8409



$$f(0) = 0$$

F S are cemetery states.

$f(x \rightarrow y) \Rightarrow k(x \rightarrow y) \cdot (1 - f(x) - s(x))$ (continue RW)
 $f(x) \rightarrow$ goes to F.
 $s(x) \rightarrow$ goes to S.

→ Committor function: RWs (P) before (C)

$$f(x) = \frac{1}{(2\pi)^{d/2} \sigma^d} \exp\left(-\frac{\|x - x_A\|^2}{2\sigma^2}\right) \quad \sigma = \frac{RA}{\sqrt{d}}$$

$$d=1 \rightarrow \frac{1}{\sqrt{2\pi} \cdot \sigma} \exp\left(-\frac{x^2}{2\sigma^2}\right) \quad \sigma = RA$$

$$\frac{1}{\sqrt{2\pi} \sigma^2} \exp\left(-\frac{11x^2}{2\sigma^2}\right)$$

ps = original

Review.

03/15/2024

$$A_1 \phi_{xx} + B_1 \phi_{xy} + C_1 \phi_{yy} + a \phi_x + b \phi_y + c \phi + d = 0$$

$$\Delta = B_1^2 - 4A_1 C_1 \begin{cases} \Delta = 0 : \text{parabolic} \\ \Delta > 0 : \text{hyperbolic} \\ \Delta < 0 : \text{elliptic.} \end{cases} \quad (x \neq y)$$

How to solve?

Linear / Non-Linear

Q) what is linearity?

$$L(\phi) = 0$$

Then, $L(c_1 \phi_1 + c_2 \phi_2) = c_1 L(\phi_1) + c_2 L(\phi_2)$

Characteristics (can't solve hyperbolic)

0

0

S, O.V. (can't solve non-linear)

0

X

Integral transformations

0

⚠ (you can integrate, may not be able to invert)

Similarity sol.

0

0

Requirement: same of dimensions

* Characteristics method only for "hyperbolic" PDEs. (must when info. travels on finite domain)

e.g.) for parabolic, $dx/dt = 0$.

1) Characteristics.

$$A \frac{\partial \phi}{\partial t} + B \frac{\partial \phi}{\partial x} + C(\phi) + D = 0$$

$$\Rightarrow \phi(x, t) \text{ can be parameterized as } \phi(x(s), t(s))$$

$$\Rightarrow \frac{\partial \phi}{\partial s} = \frac{\partial \phi}{\partial x} \left(\frac{\partial x}{\partial s} \right) + \frac{\partial \phi}{\partial t} \left(\frac{\partial t}{\partial s} \right)$$

$$\Rightarrow \frac{\partial \phi}{\partial t} + \left(\frac{B}{A} \frac{\partial \phi}{\partial x} + \frac{C}{A} \phi + \frac{D}{A} \right) = 0$$

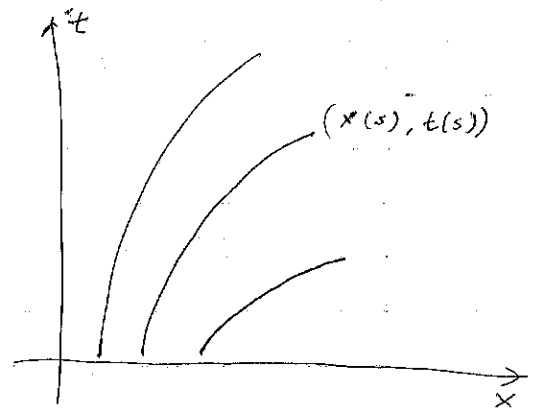
$$\left\{ \begin{aligned} \frac{\partial x}{\partial s} - \frac{B}{A} \frac{\partial t}{\partial s} &= 0 \\ \frac{\partial \phi}{\partial s} &= - \frac{C+D}{A} \frac{\partial t}{\partial s} \end{aligned} \right.$$

choose $t = s \rightarrow \frac{\partial t}{\partial s} = 1$

$$\frac{dx}{ds} = \frac{B}{A}$$

$$\frac{d\phi}{ds} = - \frac{C+D}{A}$$

→ Two ODEs



Buyers? eqns
How to solve
How to parameterize

How to parameterize

Method of characteristics

How to solve
How to parameterize

fl. 1,

~~Initial~~

fl. 1, 2
fl. 1, 2
fl. 1, 2

fl. 1, 2
fl. 1, 2

fl. 1, 2

E.g.) Burgers eq. $\partial u / \partial t + u \partial u / \partial x = 0$

$$dx/dt|_z = u \quad du/dt|_z = 0$$

depends on initial condition of ~~flow~~

• Separation of variables. — Must be Linear

Dependent variable is

Independent variable, x, y

$$u = X(x) \cdot Y(y)$$

Similarity (scaling property)

PDE \rightarrow ODE(η).

$$\eta = \frac{x}{At^n} \quad \tilde{T} = Bt^m F(\eta)$$



PDE (plg η)



ODE in $F(\eta)$

Use B.C. to (n, m)

$$\eta = \frac{x}{2\sqrt{at}}$$

|||

Fourier transforms

Contracted!